

# Graph Structure Learning for Graph Neural Networks

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# Outline

## GNN Introduction

- Why Graphs?
- Graph Neural Networks: Foundations and Models

## GSL Foundations

- Why Graph Structure Learning?
- Unsupervised GSL
- Supervised GSL

## GSL4GNN

- Why GSL for GNNs?
- Learning Discrete Graph Structures for GNNs
- Learning Weighted Graph Structures for GNNs
- Connections to Other Problems
- Future Directions and Conclusions

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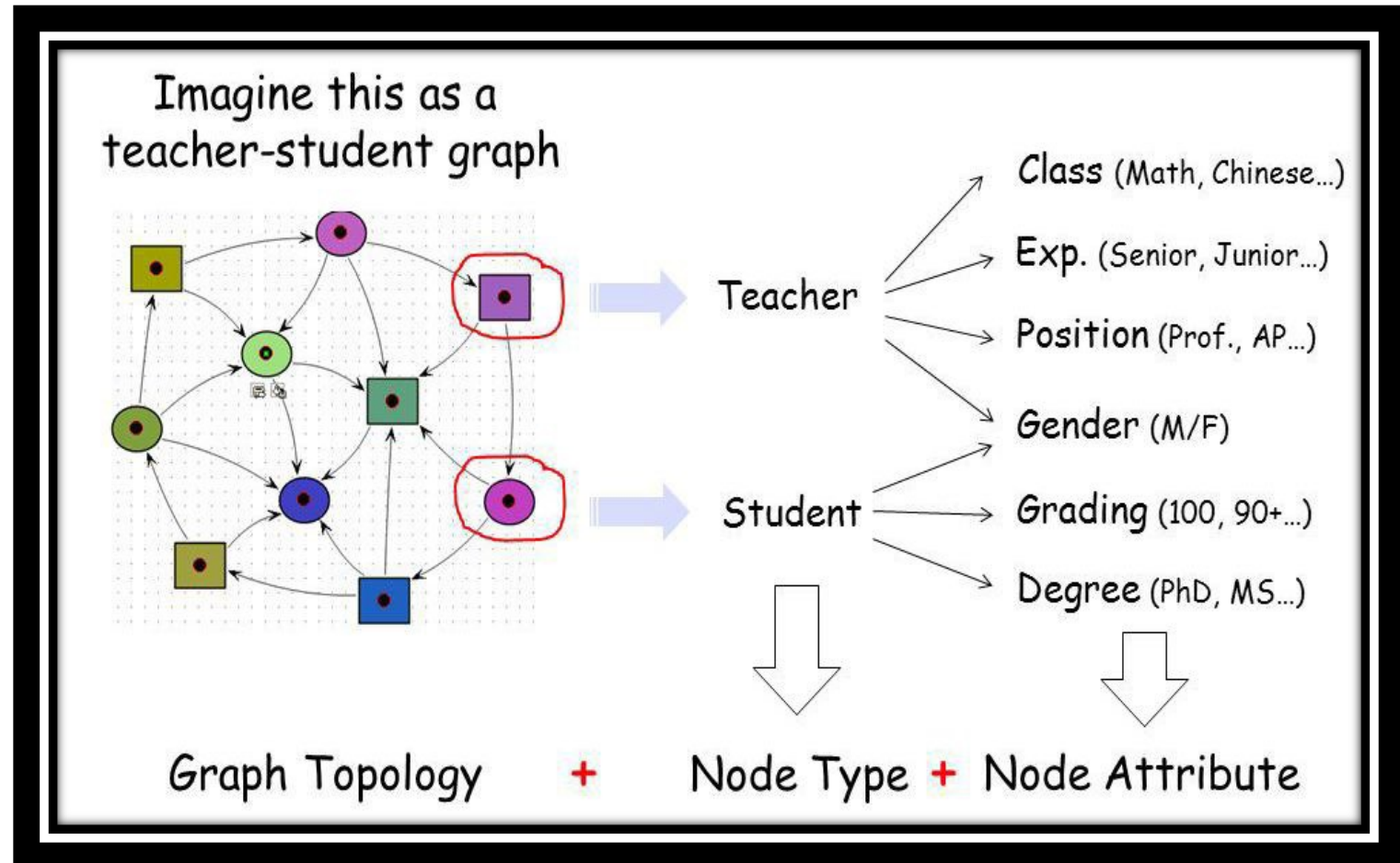
# **GNN**

## **Introduction**

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# Why Graphs?

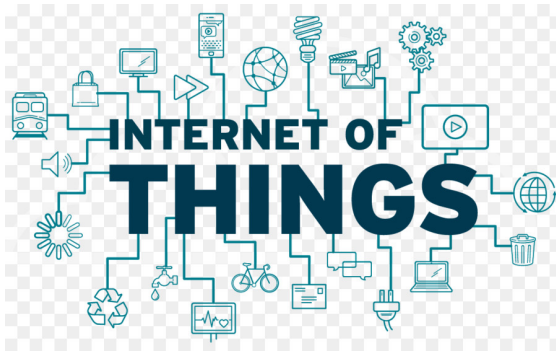
- Graphs are a general language for describing and modeling complex systems



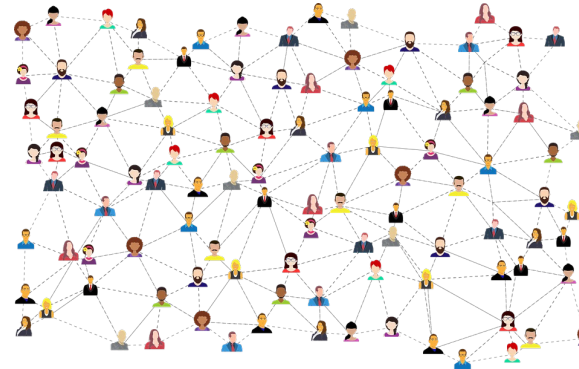
Graph = Graph Topology + Node Type + Node Attribute + Edge Type + Edge Attribute



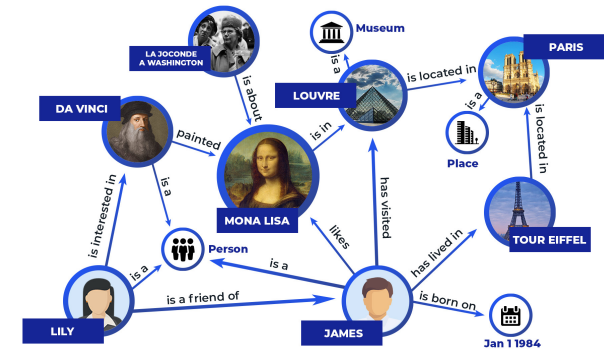
# Graph-structured Data Are Ubiquitous



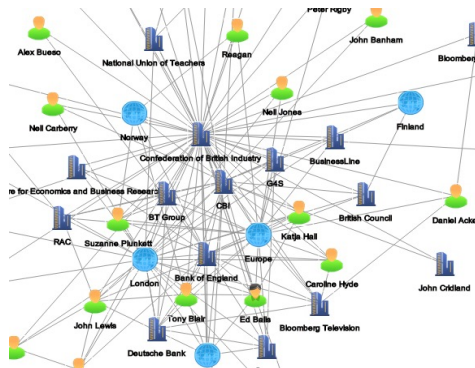
IOT graphs



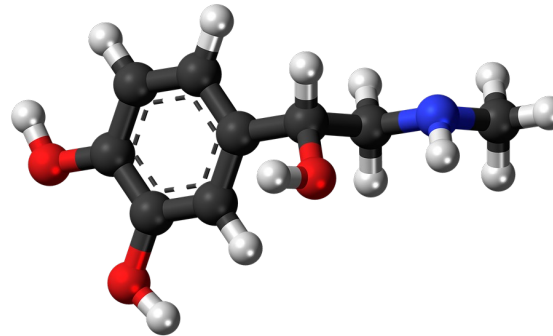
Social networks



Knowledge graphs



Financial transactions



Biomedical graphs



Scene graphs

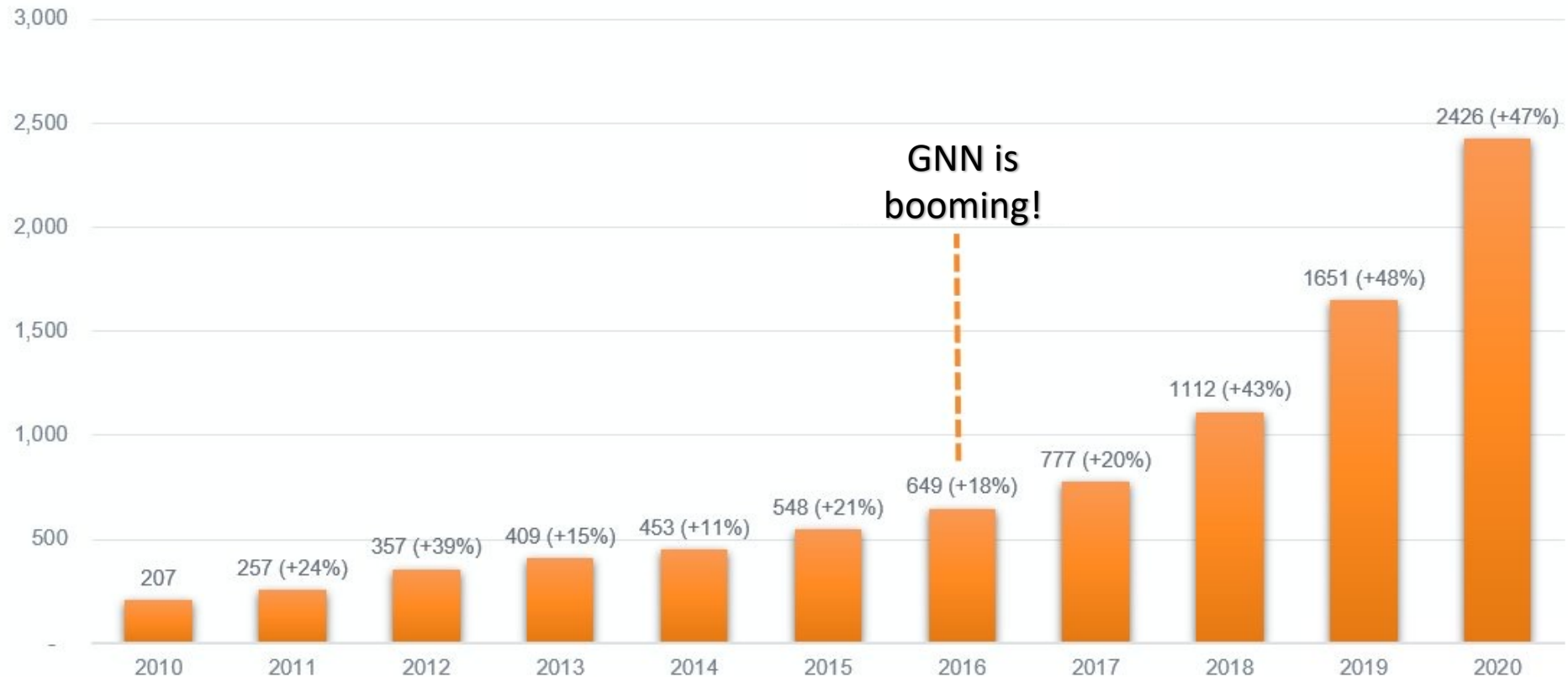
Graph = Graph Topology + Node Type + Node Attribute + Edge Type + Edge Attribute

# Graph Machine Learning: Recent Trending

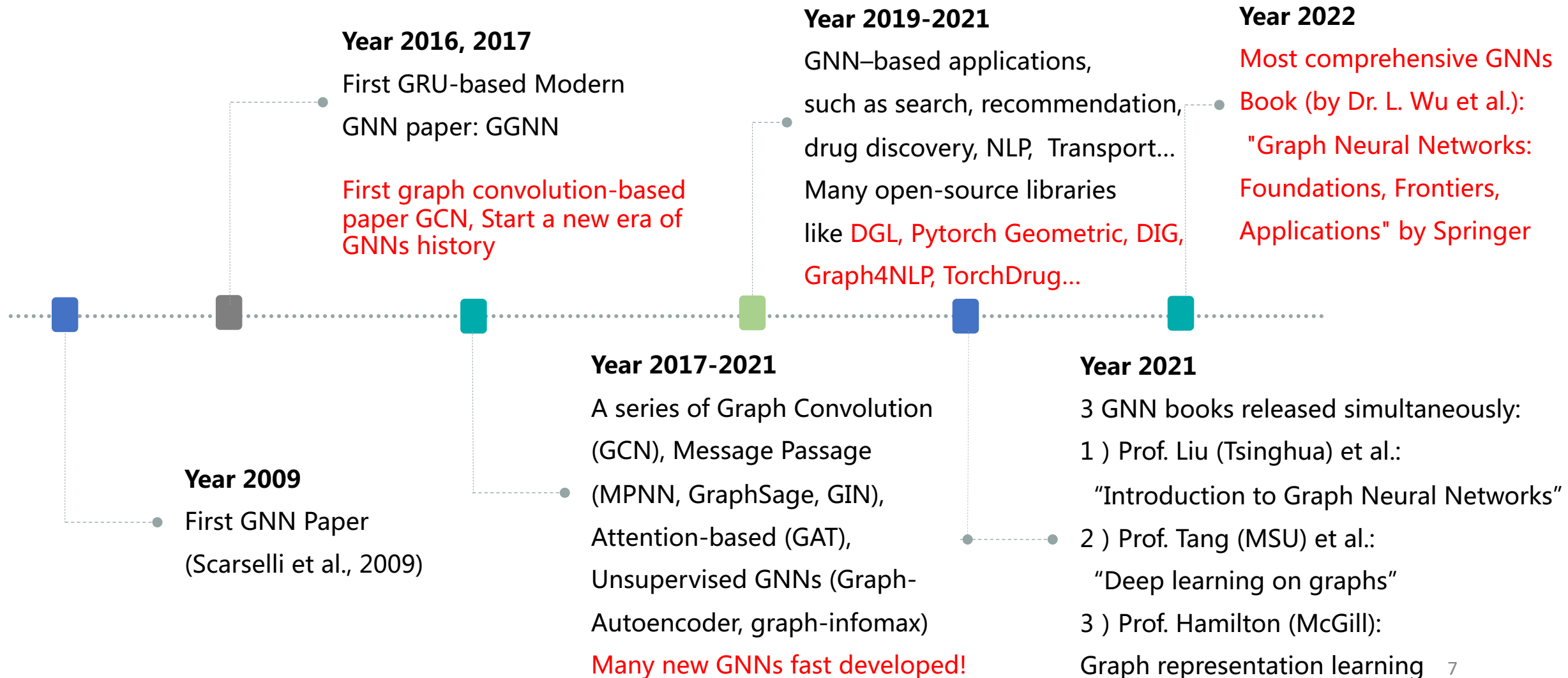
Graph Machine Learning is on fire 🔥



Number of papers with 'graph' in title (ArXiv).



# Graph Neural Networks: A Brief History



# Machine Learning on Graphs Tasks

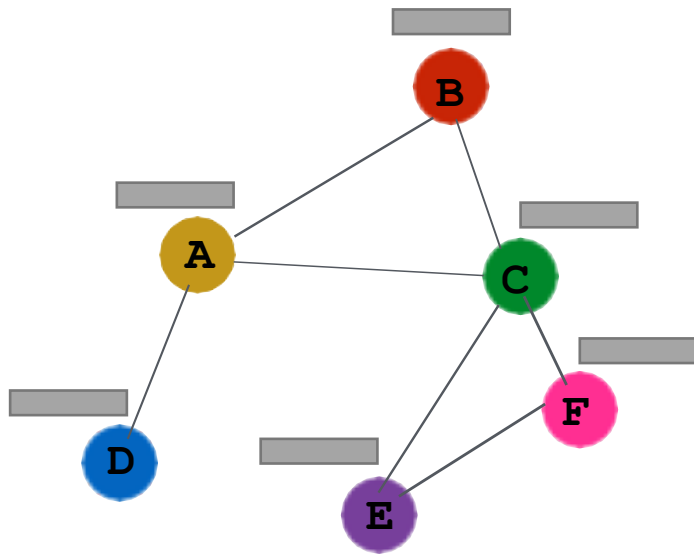
## Classical ML tasks on graphs:

- Node classification
  - Predict a type of a given node
- Link prediction
  - Predict whether two nodes are linked
- Community detection
  - Identify densely linked clusters of nodes
- Graph similarity
  - How similar are two (sub)graphs

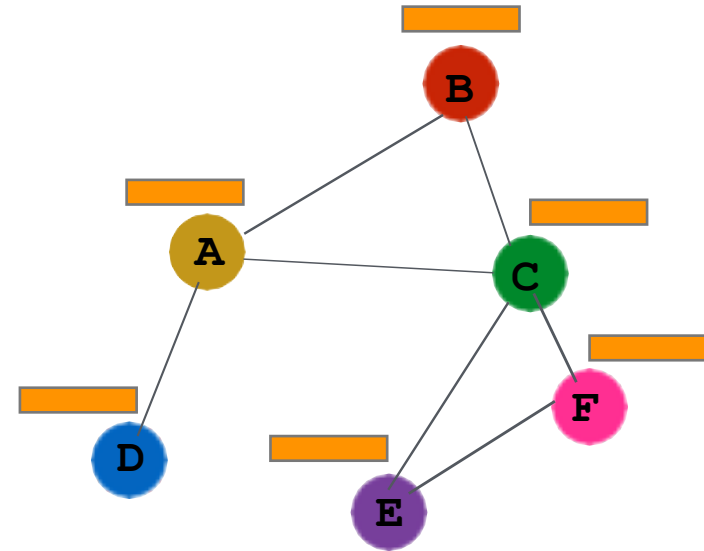
## Recent ML tasks on graphs:

- Expressive power of GNNs
  - Theoretical understanding
- Scalability of GNNs
  - Sampling paradigms for scaling up
- Adversarial robustness of GNNs
  - Adversarial attacks and provable robustness
- Graph structure learning for GNNs
  - Learning optimal graph structures for GNNs

# Modeling Graphs with Graph Neural Networks



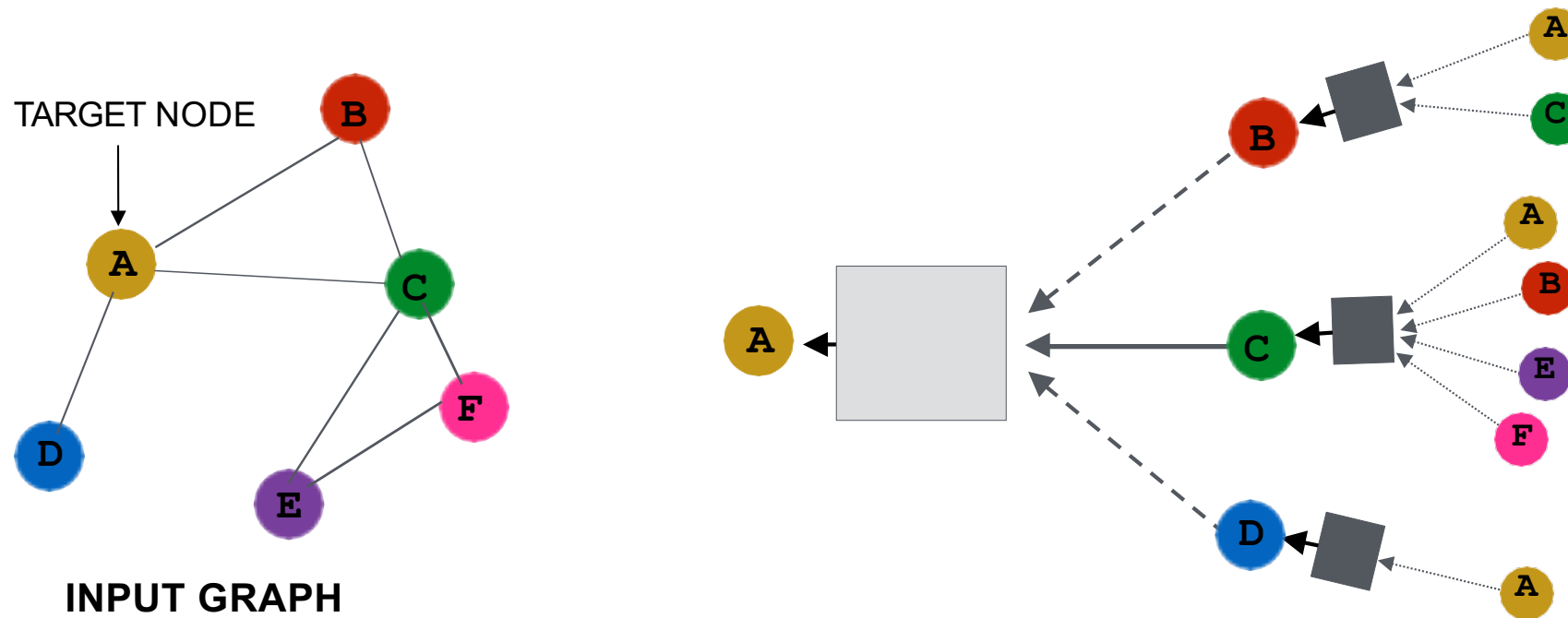
Input representations of nodes/edges



Updated representations of nodes/edges

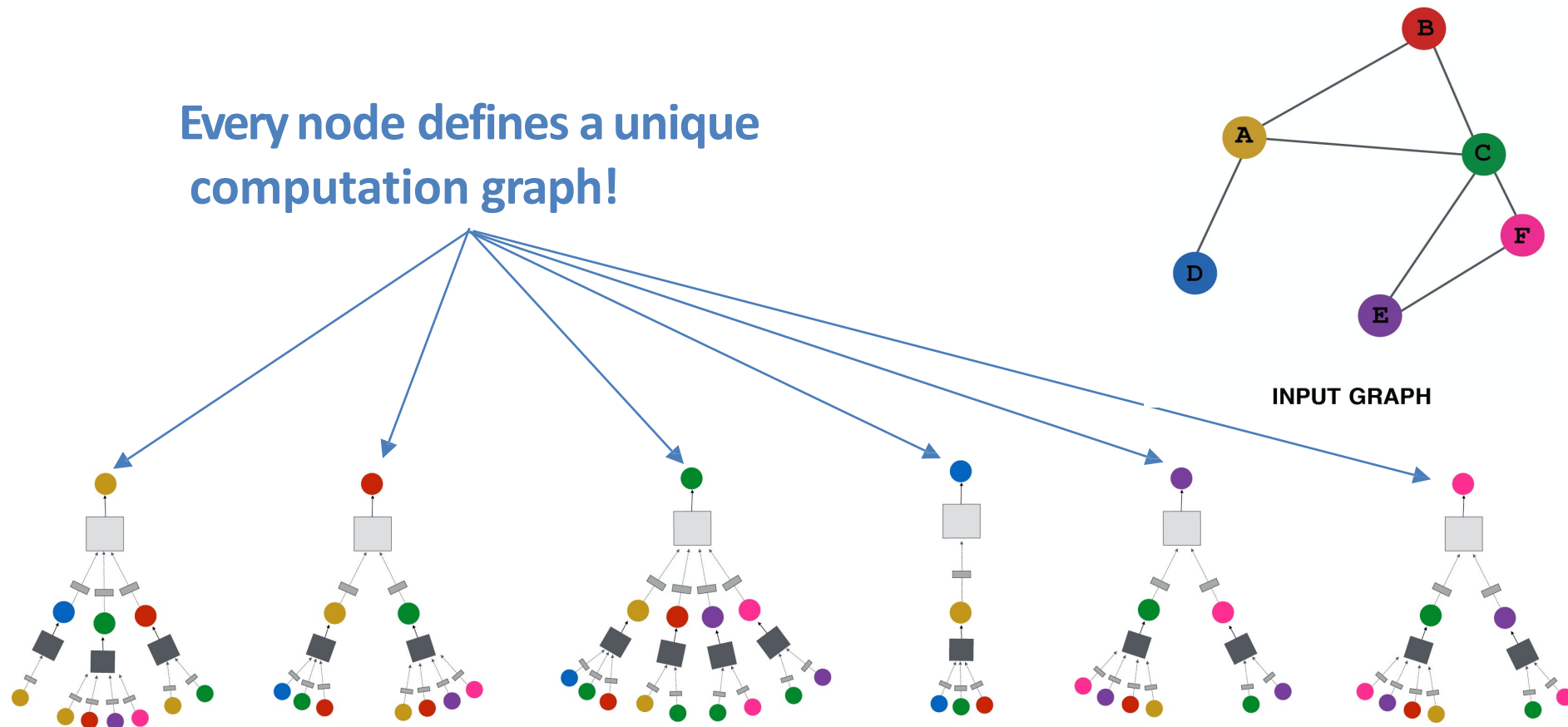
# Graph Neural Networks: Basic Model

- **Key idea:** Generate node embeddings based on local neighborhoods.



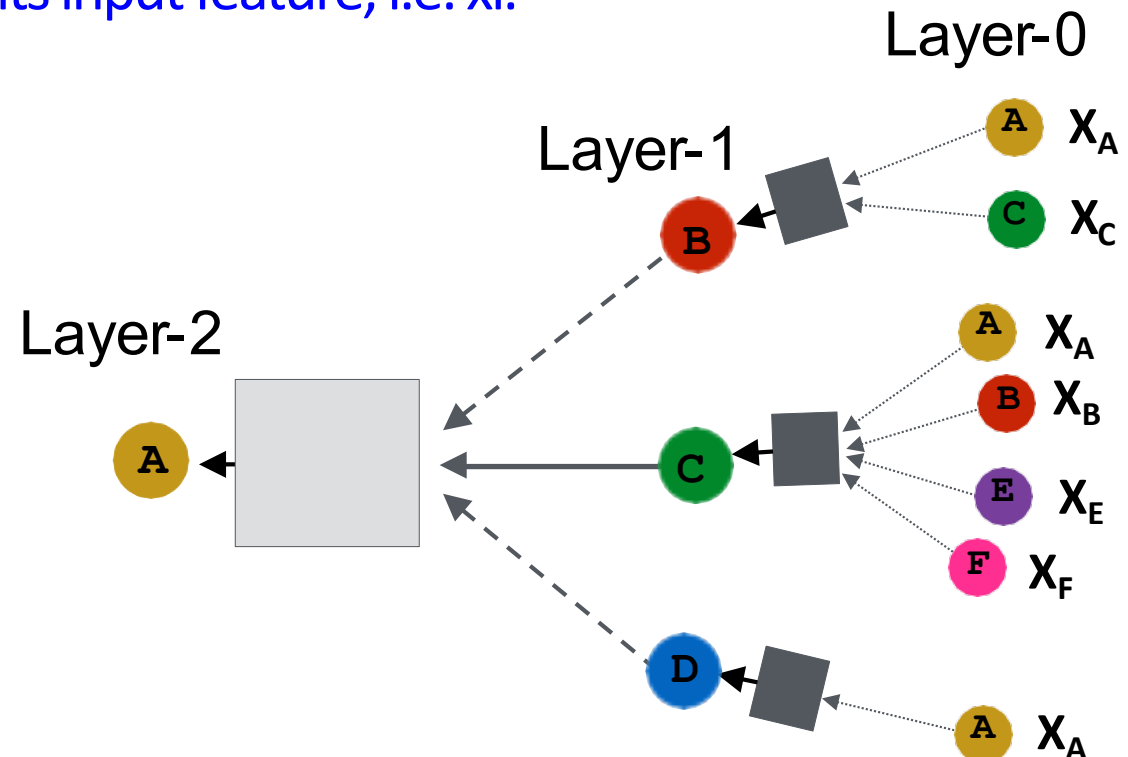
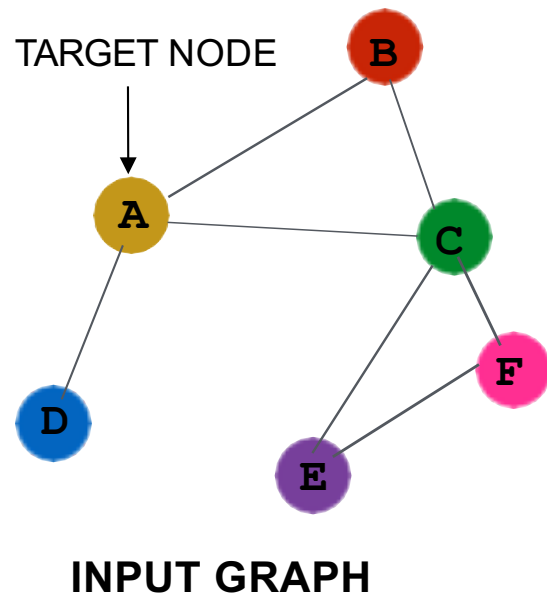
# GNN Model: Neighborhood Aggregation

- **Intuition:** Network neighborhood defines a computation graph



# GNN Model: Neighborhood Aggregation

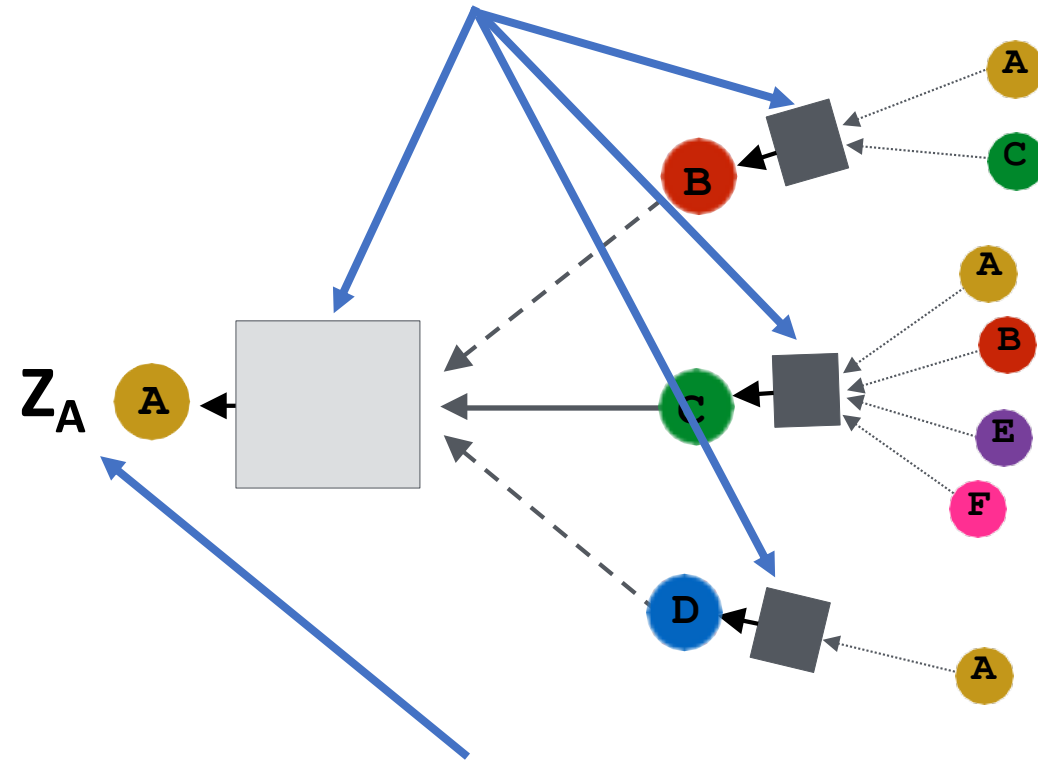
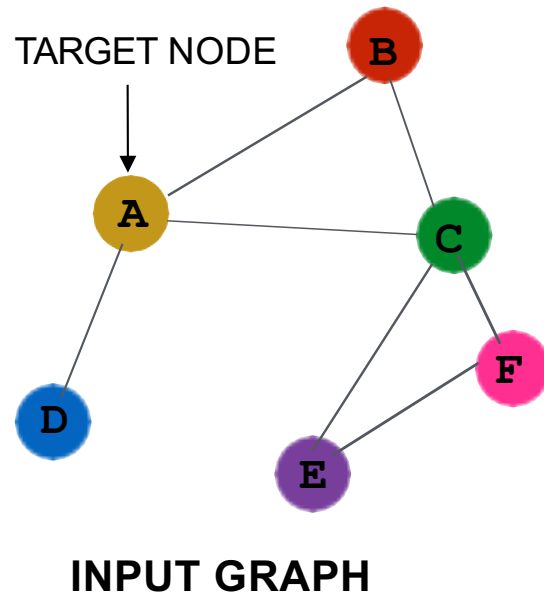
- Nodes have embeddings at each layer.
- Model can have arbitrary depth.
- “layer-0” embedding of node  $i$  is its input feature, i.e.  $x_i$ .





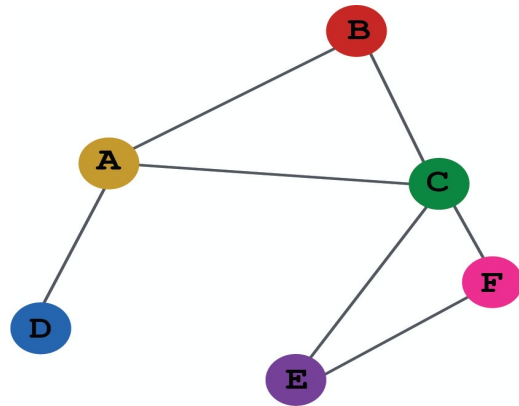
# Overview of GNN Model

1) Define node aggregation and update functions



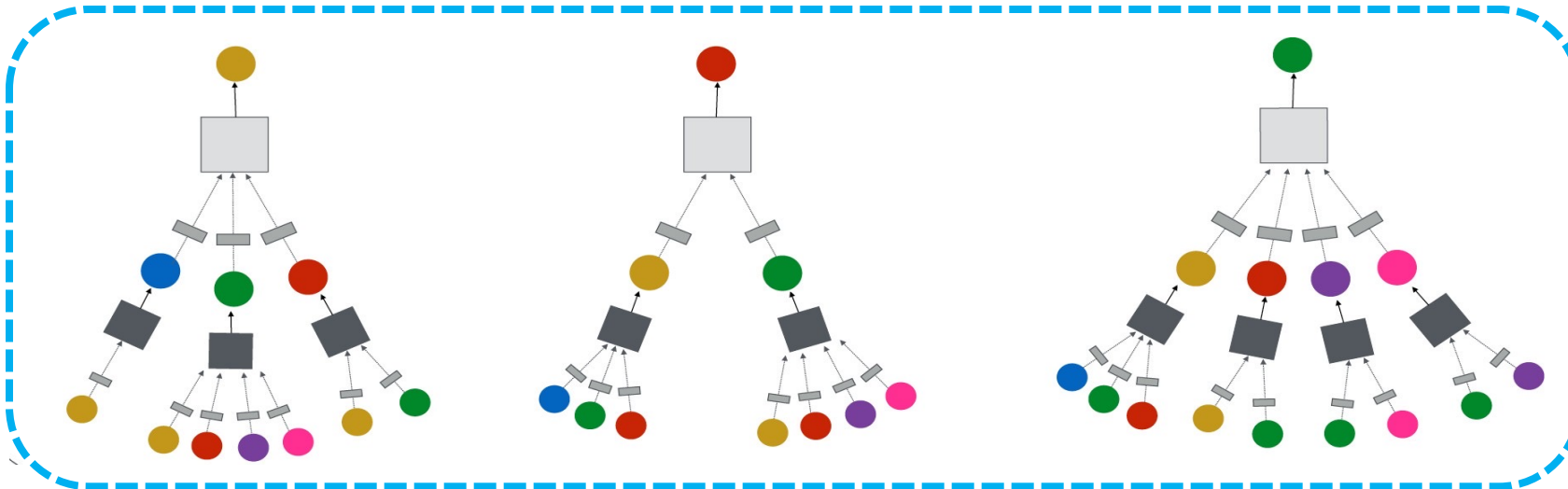
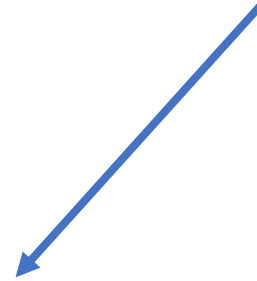
2) Define a loss function on the embeddings,  $L(\mathbf{z}_v)$

# Overview of GNN Model

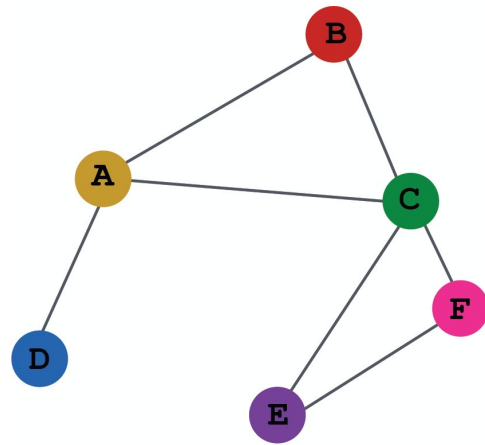


INPUT GRAPH

3) Train on a set of nodes, i.e., a batch of computation graphs



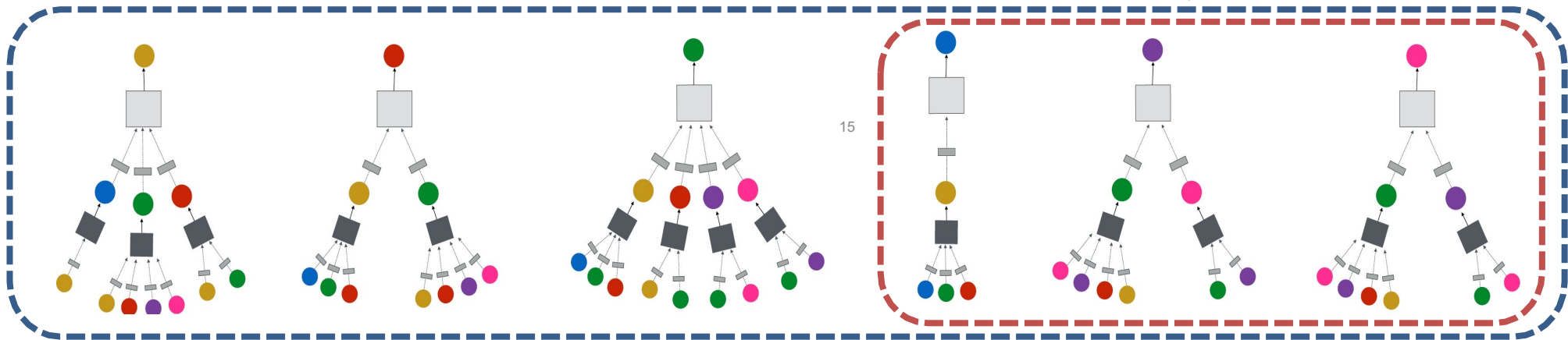
# Overview of GNN Model



INPUT GRAPH

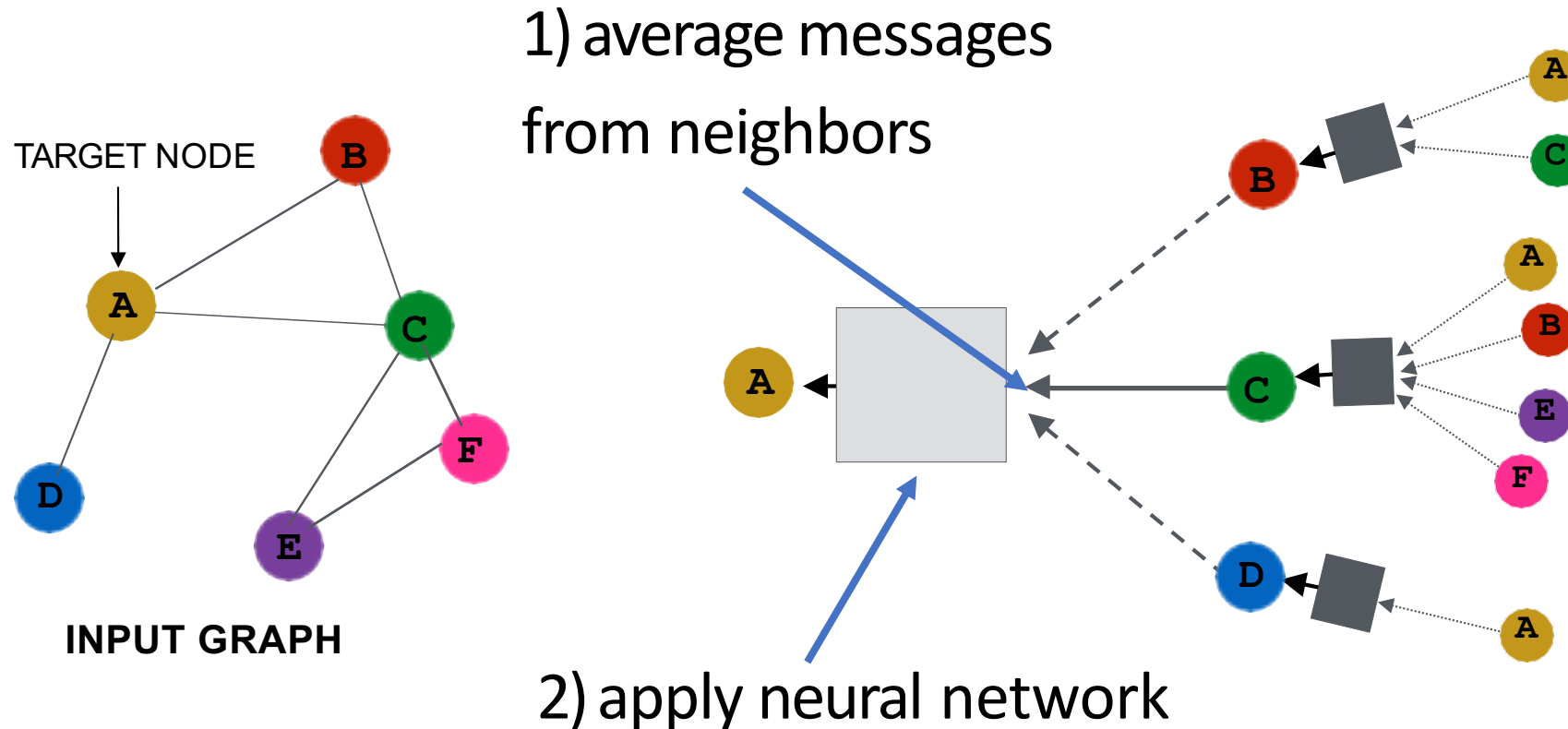
4) Generate embeddings for nodes as needed

Even for nodes we never trained on!  
– Inductive learning



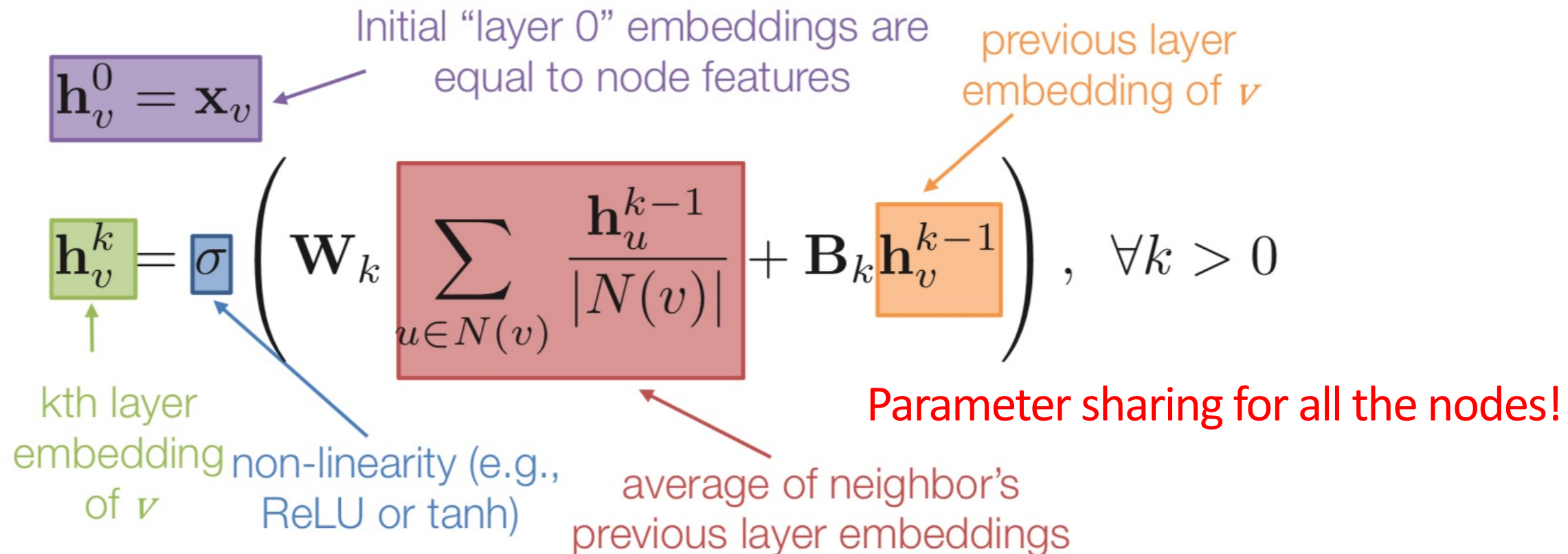
# GNN Model: A Case Study

- **Basic approach:** Average neighbor information and apply a neural network



# GNN Model: A Case Study

- **Basic approach:** Average neighbor information and apply a neural network.



# Graph Neural Networks: Foundations

- Learning node embeddings:

$$\mathbf{h}_i^{(l)} = f_{\text{filter}}(A, \mathbf{H}^{(l-1)})$$

Updated node embeddings

A graph filter

adjacency matrix

Input node embeddings

$f_{\text{filter}}(\cdot, \cdot)$

- Spectral-based
- Spatial-based
- Attention-based
- Recurrent-based

- Learning graph-level embeddings:

$$A', \mathbf{H}' = f_{\text{pool}}(A, \mathbf{H})$$

A small graph w/  
fewer nodes

New node embeddings

Input graph

Input node embeddings

$f_{\text{pool}}(\cdot, \cdot)$

- Flat Graph Pooling (i.e. Max, Ave, Min)
- Hierarchical Graph Pooling (i.e. Diffpool)

# Graph Neural Networks: Popular Models

- Spectral-based Graph Filters
  - GCN (Kipf & Welling, ICLR 2017), Chebyshev-GNN (Defferrard et al. NIPS 2016)
- Spatial-based Graph Filters
  - MPNN (Gilmer et al. ICML 2017), GraphSage (Hamilton et al. NIPS 2017)
  - GIN (Xu et al. ICLR 2019)
- Attention-based Graph Filters
  - GAT (Velickovic et al. ICLR 2018)
- Recurrent-based Graph Filters
  - GGNN (Li et al. ICLR 2016)

# GNN Model: Quick Summary

- **Key idea:** generate node embeddings by aggregating neighborhood information.
  - Allows for parameter sharing in the encoder
  - Allows for inductive learning

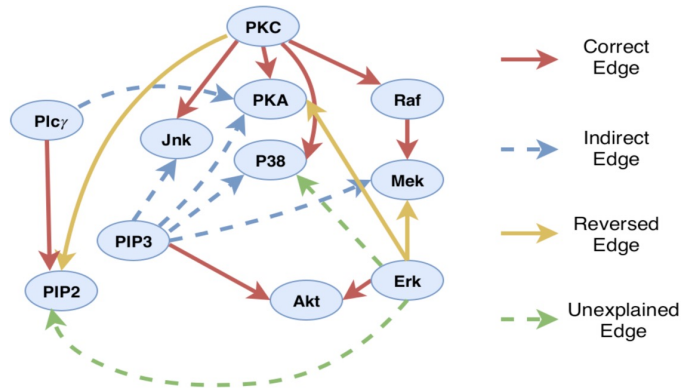


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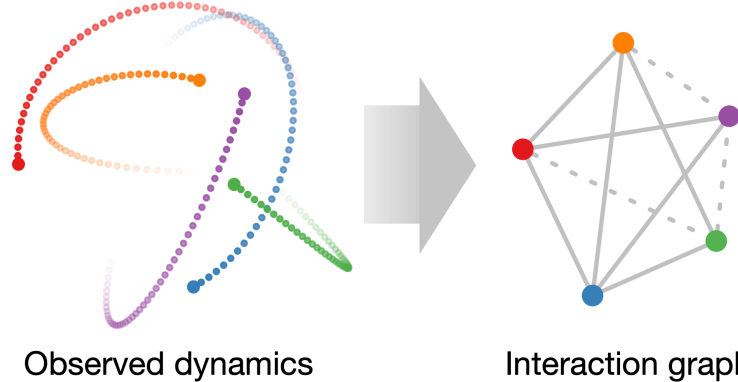
# **GSL Foundations**

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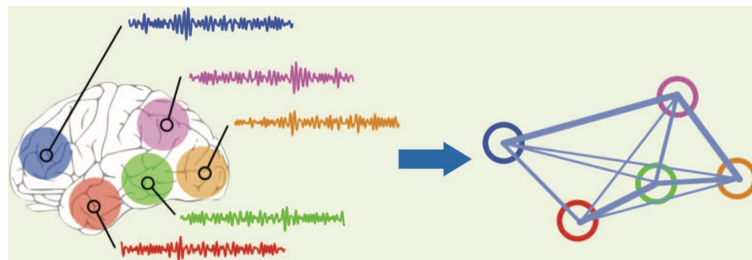
# Why Graph Structure Learning?



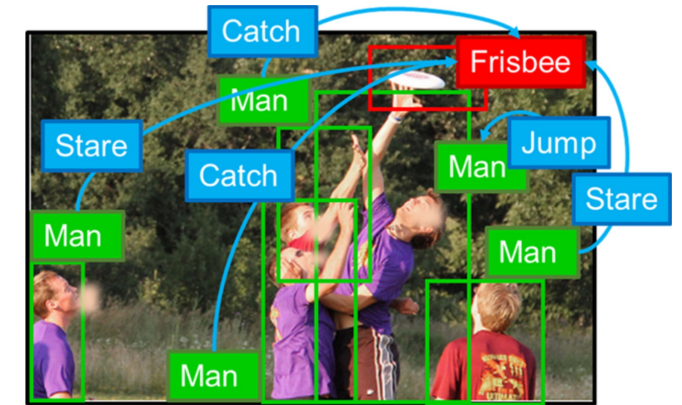
Estimating protein signaling network (Yu et al., ICML 2019)



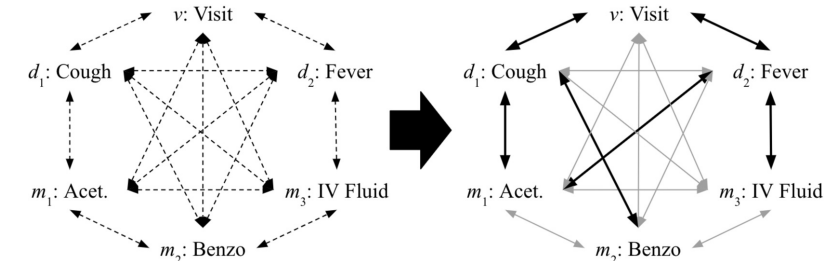
Relational inference for interacting systems (Kipf et al., ICML 2018)



Inferring functional connectivity between different brain regions (Dong et al., IEEE Signal Processing Magazine 2019)

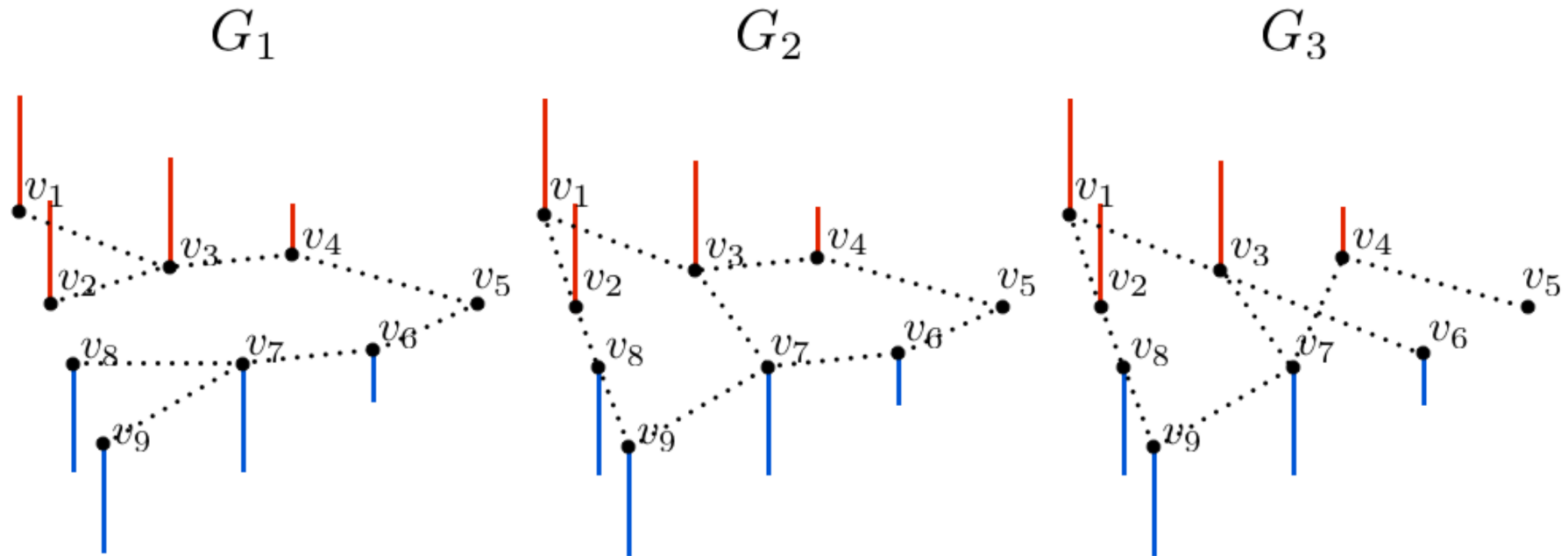


Learning relationships among visual objects (Zhu et al., Multimedia Tools and Applications 2020)



Learning the graphical structure of electronic health records (Choi et al., AAAI 2020)

# Unsupervised GSL from Smooth Signals



Signals residing on graphs, graph  $G_1$  has the best smoothness property.

# Unsupervised GSL from Smooth Signals: Fitness

Node feature reconstruction using neighboring node features

$$\sum_i \left\| \mathbf{X}_i - \sum_j A_{i,j} \mathbf{X}_j \right\|^2$$

where  $\sum_j A_{i,j} = 1, A_{i,j} \geq 0$

Weighted sum of the squared distance from each node to the weighted average of its neighbors

OR

$$\sum_i \left\| D_{i,i} \mathbf{X}_i - \sum_j A_{i,j} \mathbf{X}_j \right\|^2 = \|\mathbf{L}\mathbf{X}\|_F^2$$

where  $D_{i,i} = \sum_j A_{i,j}$

# Unsupervised GSL from Smooth Signals: Smoothness

$$\Omega(\mathbf{A}, \mathbf{X}) = \frac{1}{2} \sum_{i,j} \boxed{A_{i,j} ||\mathbf{X}_i - \mathbf{X}_j||^2} = \text{tr}(\mathbf{X}^\top \mathbf{L} \mathbf{X})$$

Forcing neighboring vertices to have similar features

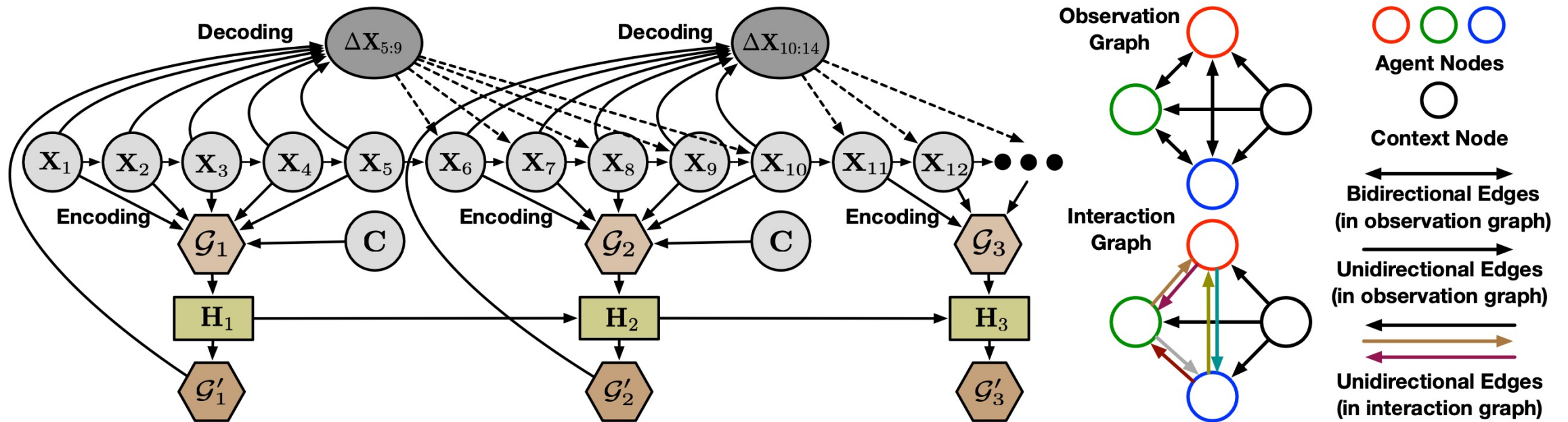
# Unsupervised GSL from Smooth Signals: Connectivity and Sparsity

$$\boxed{-\alpha \vec{1}^\top \log(\mathbf{A} \vec{1})} + \boxed{\beta ||\mathbf{A}||_F^2}$$

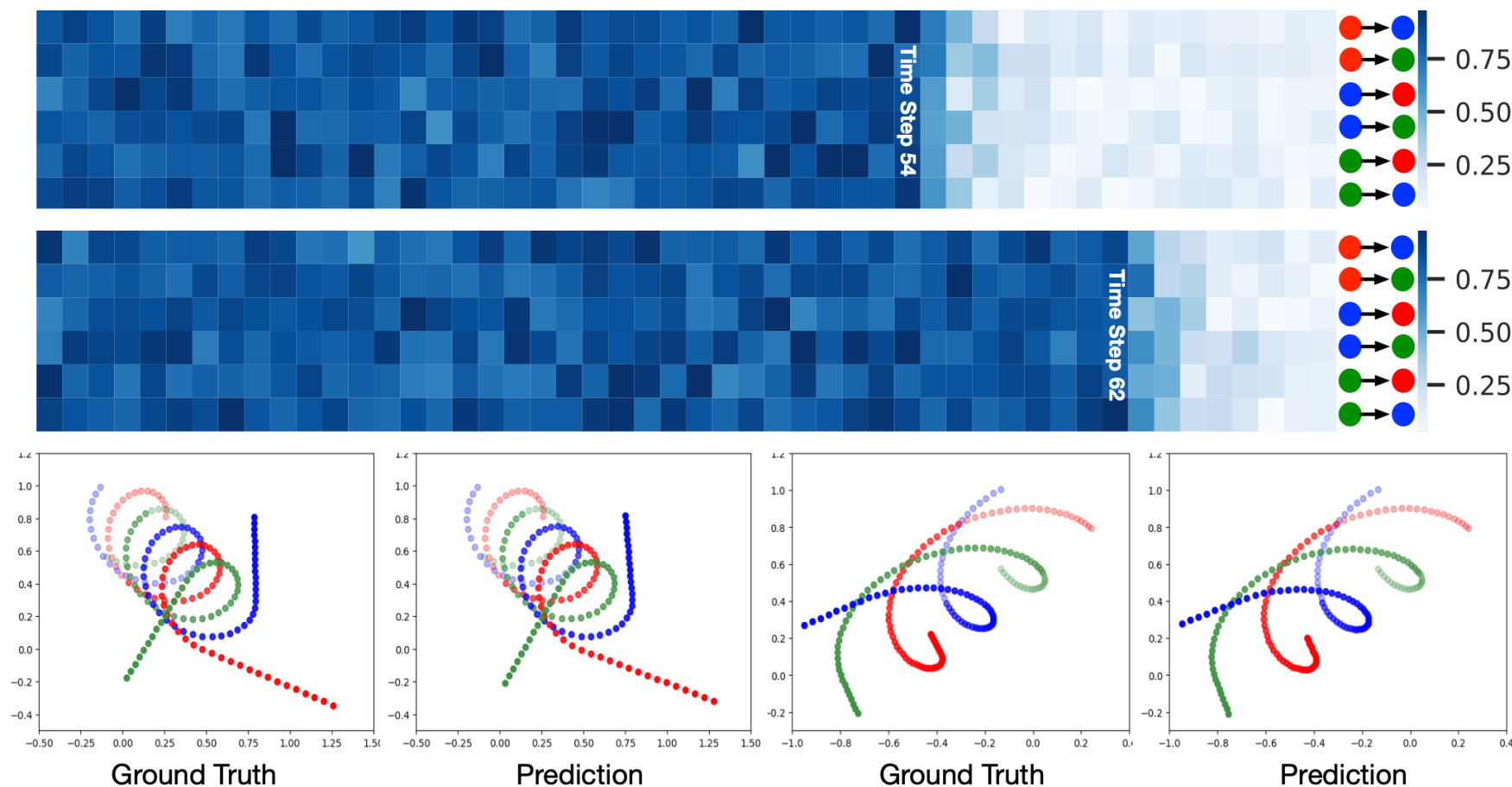
Connectivity

Sparsity

# Supervised GSL for Interacting Systems [Li et al., NeurIPS 2020]



# Supervised GSL for Interacting Systems [Li et al., NeurIPS 2020]



Visualization of latent interaction graph evolution and particle trajectories.



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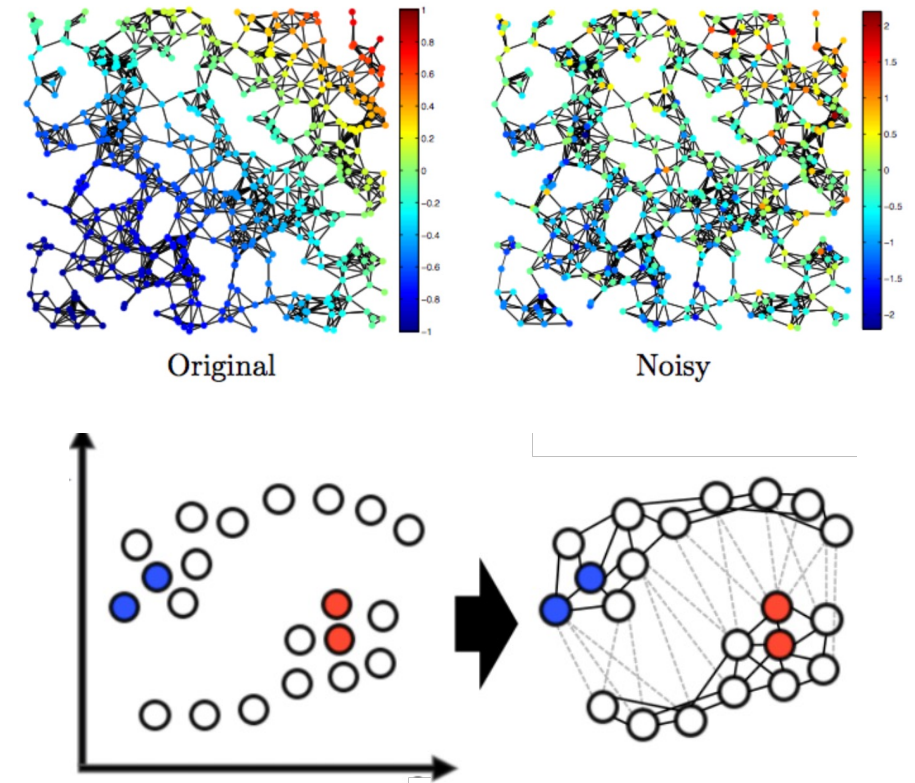
# **GSL4GNN**

## **Foundations**

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# Why GSL for GNNs?

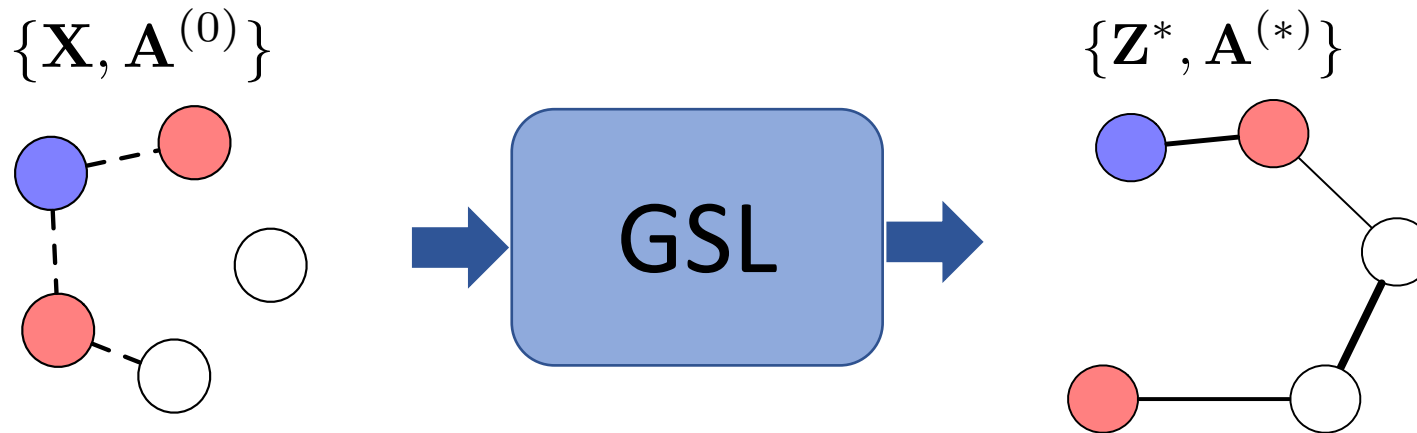
- GNNs are powerful, unfortunately, it requires **graph-structured data available**.
- **Questionable if the given intrinsic graph-structures are optimal** (i.e., noisy, incomplete, etc.) for downstream tasks.
- Many applications (e.g., NLP tasks) may only have **non-graph structured data or even just the original feature matrix**, requiring additional graph construction.



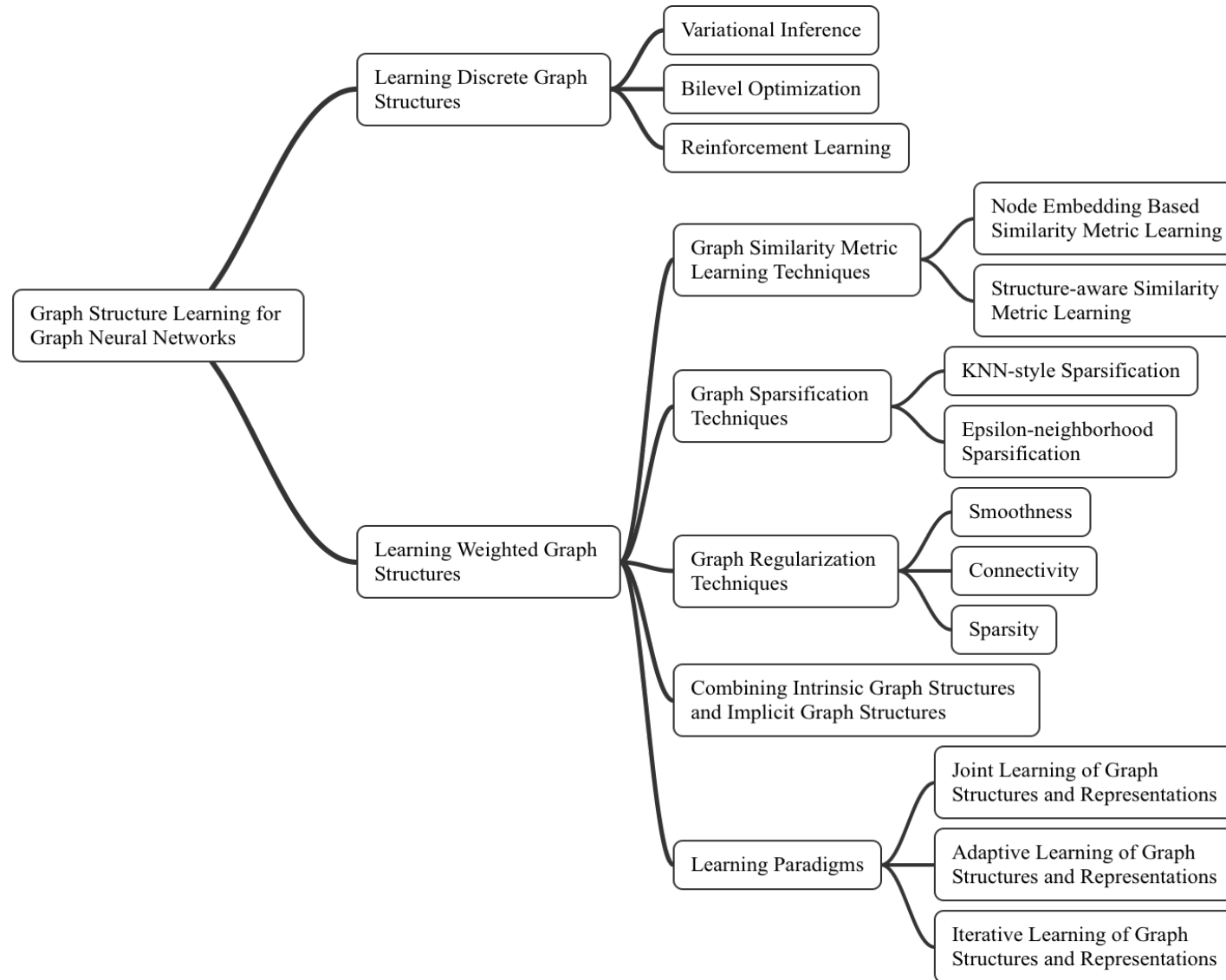
# GSL4GNN Formulation

**Input:** a set of  $n$  nodes associated with a feature matrix  $\mathbf{X} \in \mathbb{R}^{d \times n}$  and an (**optional and potentially noisy**) initial adjacency matrix  $\mathbf{A}^{(0)} \in \mathbb{R}^{n \times n}$ .

**Output:** an optimized adjacency matrix  $\mathbf{A}^{(*)} \in \mathbb{R}^{n \times n}$  and node embedding matrix  $\mathbf{Z}^* \in \mathbb{R}^{d' \times n}$  with respect to **downstream task (i.e., task-dependent loss)**.



# GSL4GNN Roadmap



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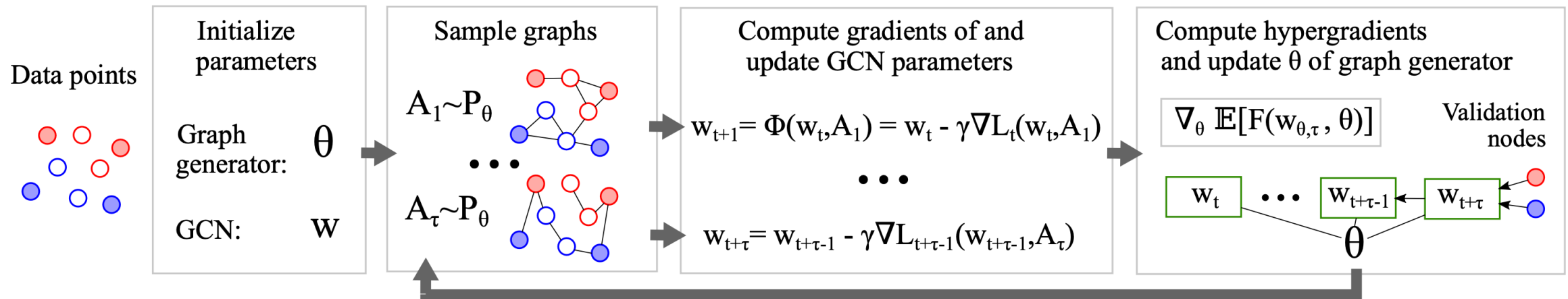
# Learning Discrete Graph Structures for GNNs

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# Learning Discrete Graph Structures for GNNs

- Sampling a **discrete** graph structure from learned probabilistic adjacency matrix.
- Joint graph structure and GNN parameters optimization (non-differentiable, **intractable to solve exactly**) via
  - Variational inference
  - Bilevel optimization
  - Reinforcement Learning
- Non-trivial to extend to inductive learning setting.

# Bilevel Optimization for GSL [Franceschi et al., ICML 2019]



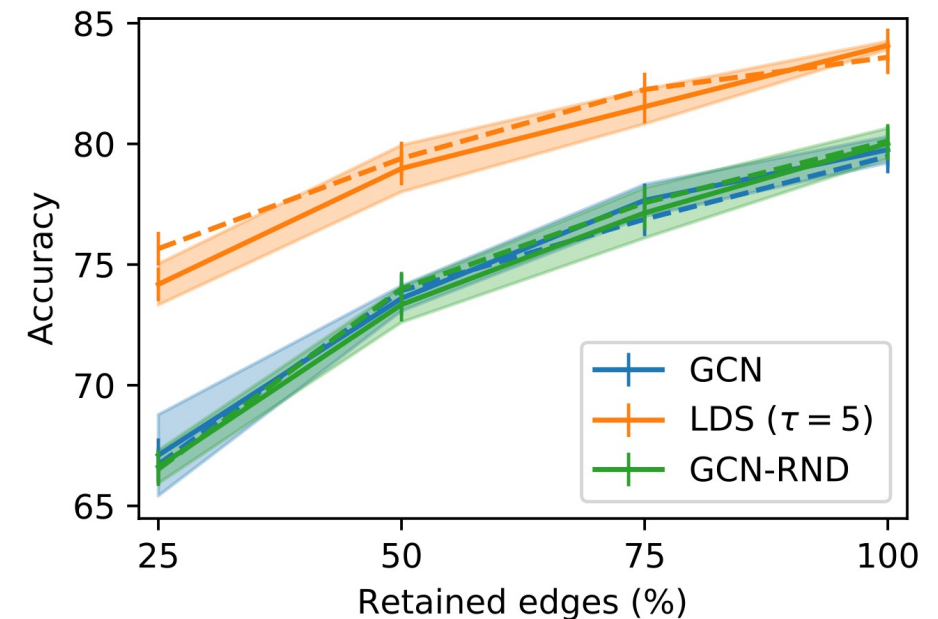
$$\min_{\theta \in \overline{\mathcal{H}}_N} \mathbb{E}_{\mathbf{A} \sim \text{Ber}(\theta)} [F(\mathbf{w}_\theta, \mathbf{A})] \quad \leftarrow \text{Outer objective for graph structure optimization}$$

such that  $\mathbf{w}_\theta = \operatorname{argmin}_{\mathbf{w}} \mathbb{E}_{\mathbf{A} \sim \text{Ber}(\theta)} [L(\mathbf{w}, \mathbf{A})] \quad \leftarrow \text{Inner objective for GNN parameters optimization}$

# Bilevel Optimization for GSL [Franceschi et al., ICML 2019]

	Wine	Cancer	Digits	Citeseer	Cora	20news	FMA
LogReg	92.1 (1.3)	<b>93.3 (0.5)</b>	85.5 (1.5)	62.2 (0.0)	60.8 (0.0)	42.7 (1.7)	37.3 (0.7)
Linear SVM	93.9 (1.6)	<b>90.6 (4.5)</b>	87.1 (1.8)	58.3 (0.0)	58.9 (0.0)	40.3 (1.4)	35.7 (1.5)
RBF SVM	<b>94.1 (2.9)</b>	<b>91.7 (3.1)</b>	86.9 (3.2)	60.2 (0.0)	59.7 (0.0)	41.0 (1.1)	<b>38.3 (1.0)</b>
RF	93.7 (1.6)	<b>92.1 (1.7)</b>	83.1 (2.6)	60.7 (0.7)	58.7 (0.4)	40.0 (1.1)	<b>37.9 (0.6)</b>
FFNN	89.7 (1.9)	<b>92.9 (1.2)</b>	36.3 (10.3)	56.7 (1.7)	56.1 (1.6)	38.6 (1.4)	33.2 (1.3)
LP	89.8 (3.7)	76.6 (0.5)	<b>91.9 (3.1)</b>	23.2 (6.7)	37.8 (0.2)	35.3 (0.9)	14.1 (2.1)
ManiReg	90.5 (0.1)	81.8 (0.1)	83.9 (0.1)	67.7 (1.6)	62.3 (0.9)	<b>46.6 (1.5)</b>	34.2 (1.1)
SemiEmb	91.9 (0.1)	89.7 (0.1)	<b>90.9 (0.1)</b>	68.1 (0.1)	63.1 (0.1)	<b>46.9 (0.1)</b>	34.1 (1.9)
Sparse-GCN	63.5 (6.6)	72.5 (2.9)	13.4 (1.5)	33.1 (0.9)	30.6 (2.1)	24.7 (1.2)	23.4 (1.4)
Dense-GCN	90.6 (2.8)	90.5 (2.7)	35.6 (21.8)	58.4 (1.1)	59.1 (0.6)	40.1 (1.5)	34.5 (0.9)
RBF-GCN	90.6 (2.3)	<b>92.6 (2.2)</b>	70.8 (5.5)	58.1 (1.2)	57.1 (1.9)	39.3 (1.4)	33.7 (1.4)
$k$ NN-GCN	93.2 (3.1)	<b>93.8 (1.4)</b>	<b>91.3 (0.5)</b>	68.3 (1.3)	66.5 (0.4)	41.3 (0.6)	<b>37.8 (0.9)</b>
$k$ NN-LDS (dense)	<b>97.5 (1.2)</b>	<b>94.9 (0.5)</b>	<b>92.1 (0.7)</b>	<b>70.9 (1.3)</b>	<b>70.9 (1.1)</b>	<b>45.6 (2.2)</b>	<b>38.6 (0.6)</b>
$k$ NN-LDS	<b>97.3 (0.4)</b>	<b>94.4 (1.9)</b>	<b>92.5 (0.7)</b>	<b>71.5 (1.1)</b>	<b>71.5 (0.8)</b>	<b>46.4 (1.6)</b>	<b>39.7 (1.4)</b>

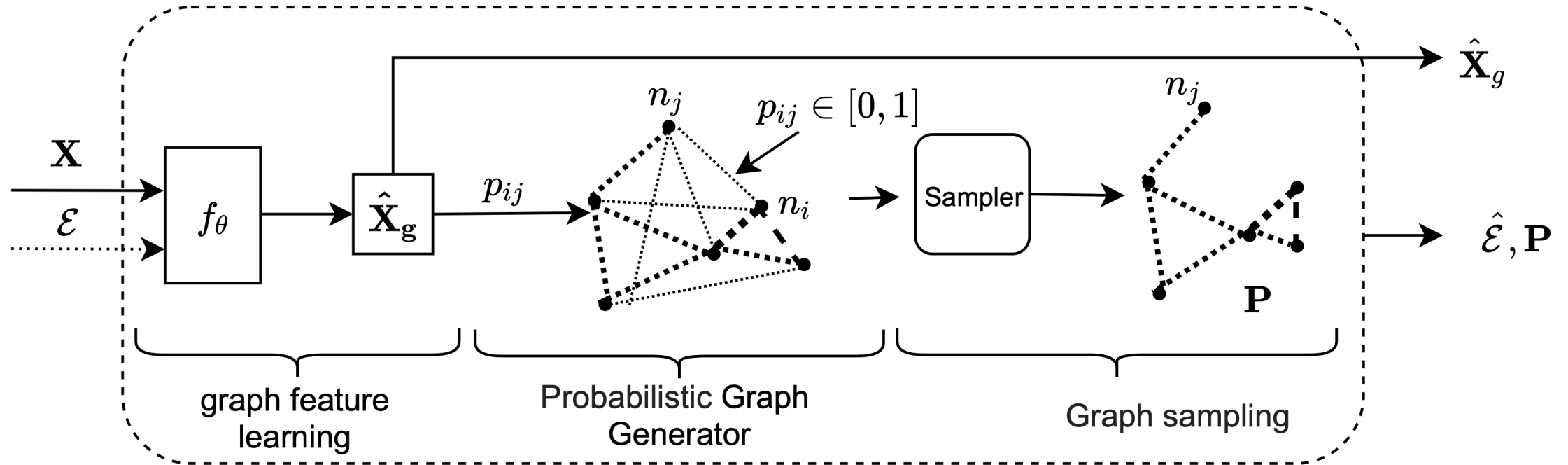
Test accuracy (in percentage) on various node classification datasets.



Val/test accuracy (in percent) for the edge deletion scenarios on Cora.



# Reinforcement Learning for GSL [Kazi et al., arXiv 2020]



Graph generator:

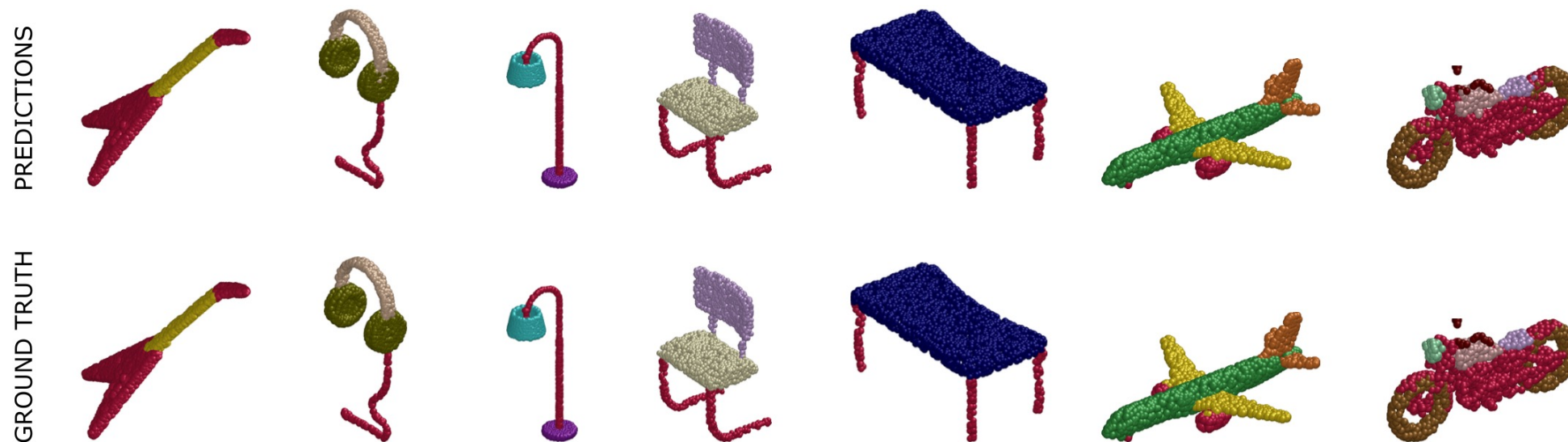
$$p_{i,j} = e^{-t||\mathbf{X}_i - \mathbf{X}_j||}$$

RL reward:

$$L_{graph} = \sum_{\alpha}^{Classes} \sum_{i \in \alpha} \delta_{\alpha}(y_i, \tilde{y}_i) \prod_{l=1}^L \prod_{j:(i,j) \in \hat{\mathcal{E}}^{(l)}} p_{ij}^{(l)},$$

$$\delta_{\alpha}(y_i, \tilde{y}_i) = \begin{cases} \text{acc}_{\alpha} - 1 & \text{if } y_i = \tilde{y}_i \\ \text{acc}_{\alpha} & \text{otherwise} \end{cases}$$

# Reinforcement Learning for GSL [Kazi et al., arXiv 2020]



Point cloud segmentation results on ShapeNet dataset.

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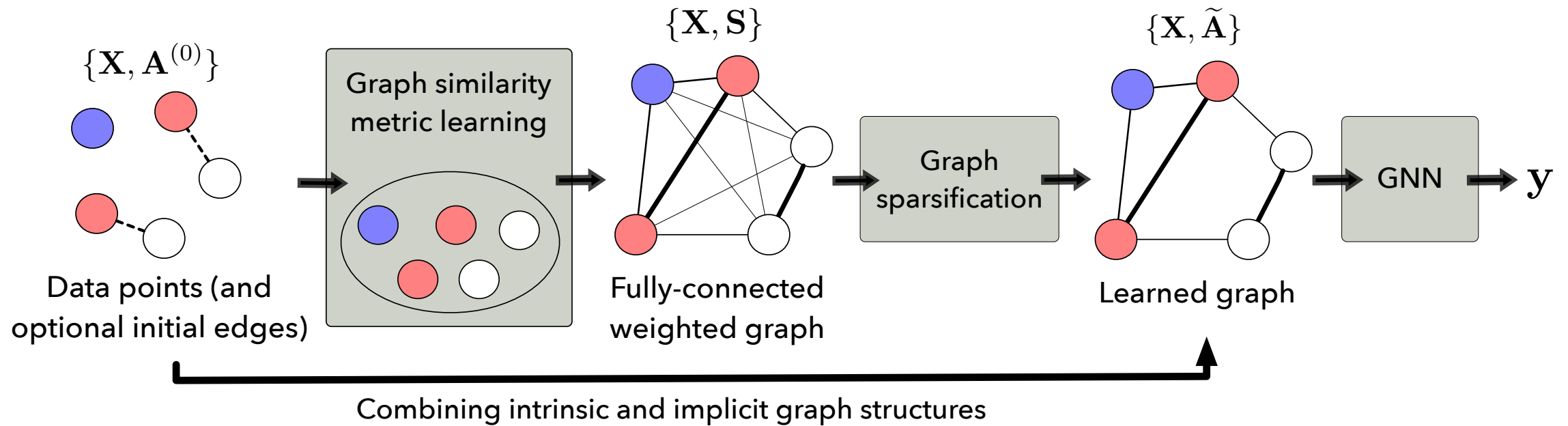
# **Learning Weighted Graph Structures for GNNs**

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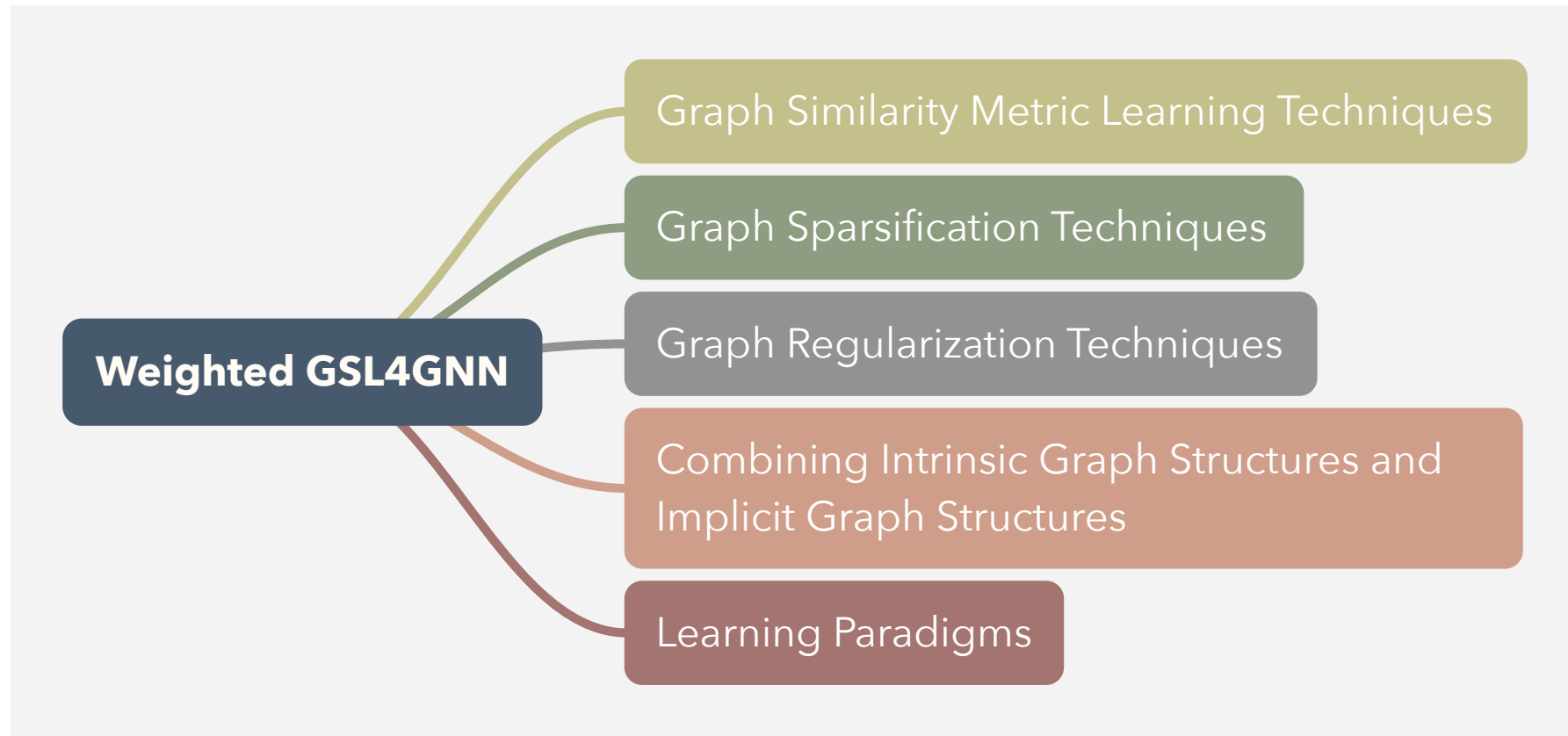
# Learning Weighted Graph Structures for GNNs

- Learning a **weighted adjacency matrix** to represent graph structure.
- Joint graph structure and GNN parameters optimization (differentiable, **more tractable**) via SGD techniques.
- Weighted adjacency matrix captures richer information.
- Handling both transductive and inductive learning settings.

# Weighted GSL4GNN Overview

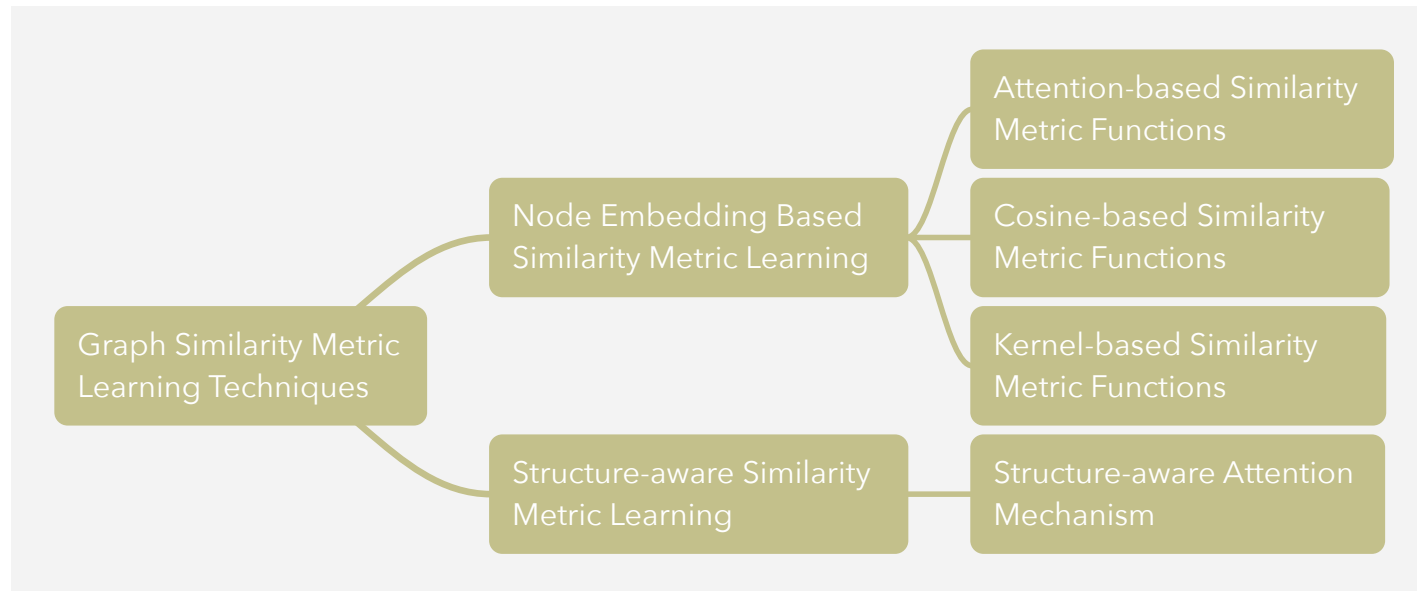


# Weighted GSL4GNN Outline



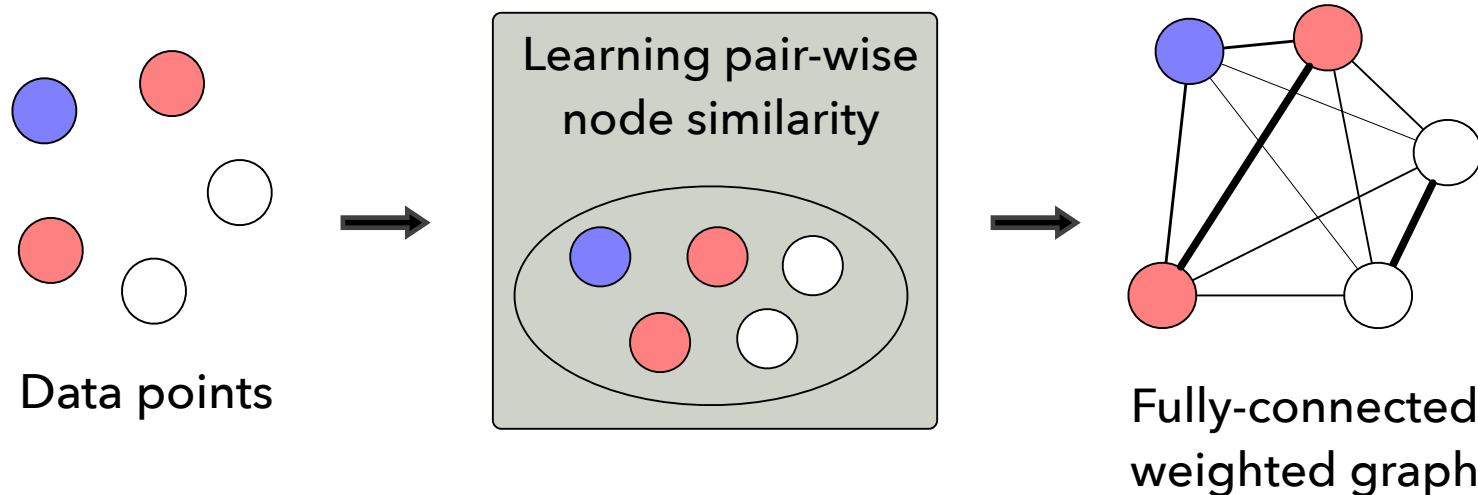
# Graph Similarity Metric Learning Techniques

- Graph structure learning as **similarity metric learning** (in the node embedding space)
- Enabling **inductive learning**
- Various metric functions



# Node Embedding Based Similarity Metric Learning

- Learning a weighted adjacency matrix by computing the **pair-wise node similarity** in the embedding space
- Common metrics functions
  - Attention-based similarity metric functions
  - Cosine-based similarity metric functions
  - Kernel-based similarity metric functions





# Attention-based Similarity Metric Functions

Variant 1)

$$S_{i,j} = (\mathbf{v}_i \odot \mathbf{u})^T \mathbf{v}_j$$

Node feature vector

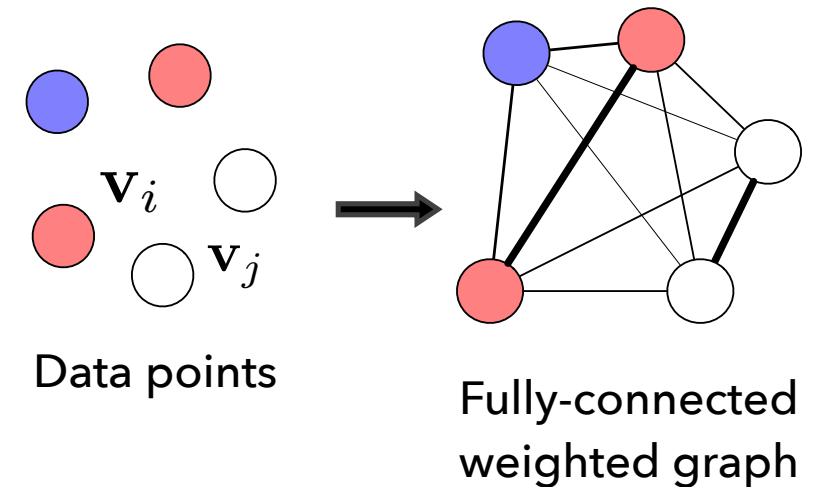
Non-negative learnable weight vector

Variant 2)

$$S_{i,j} = \text{ReLU}(\mathbf{W} \mathbf{v}_i)^T \text{ReLU}(\mathbf{W} \mathbf{v}_j)$$

Enforcing sparsity

Learnable weight matrix



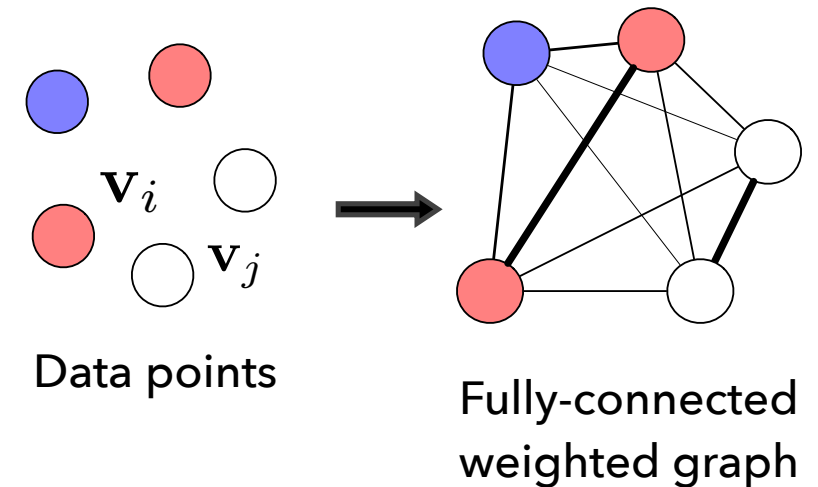
# Cosine-based Similarity Metric Functions

$$S_{i,j}^p = \cos(\mathbf{w}_p \odot \mathbf{v}_i, \mathbf{w}_p \odot \mathbf{v}_j)$$

Learnable weight vector

$$S_{i,j} = \frac{1}{m} \sum_{p=1}^m S_{ij}^p$$

Multi-head similarity scores

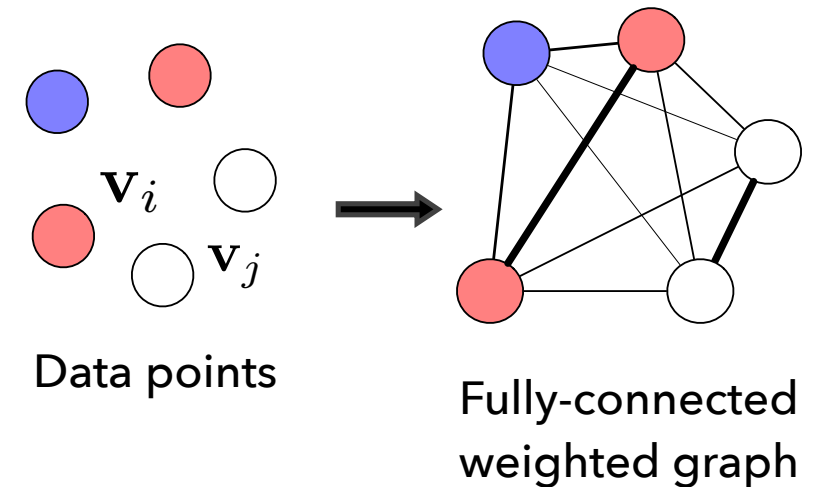


# Kernel-based Similarity Metric Functions

Mahalanobis distance between node embeddings

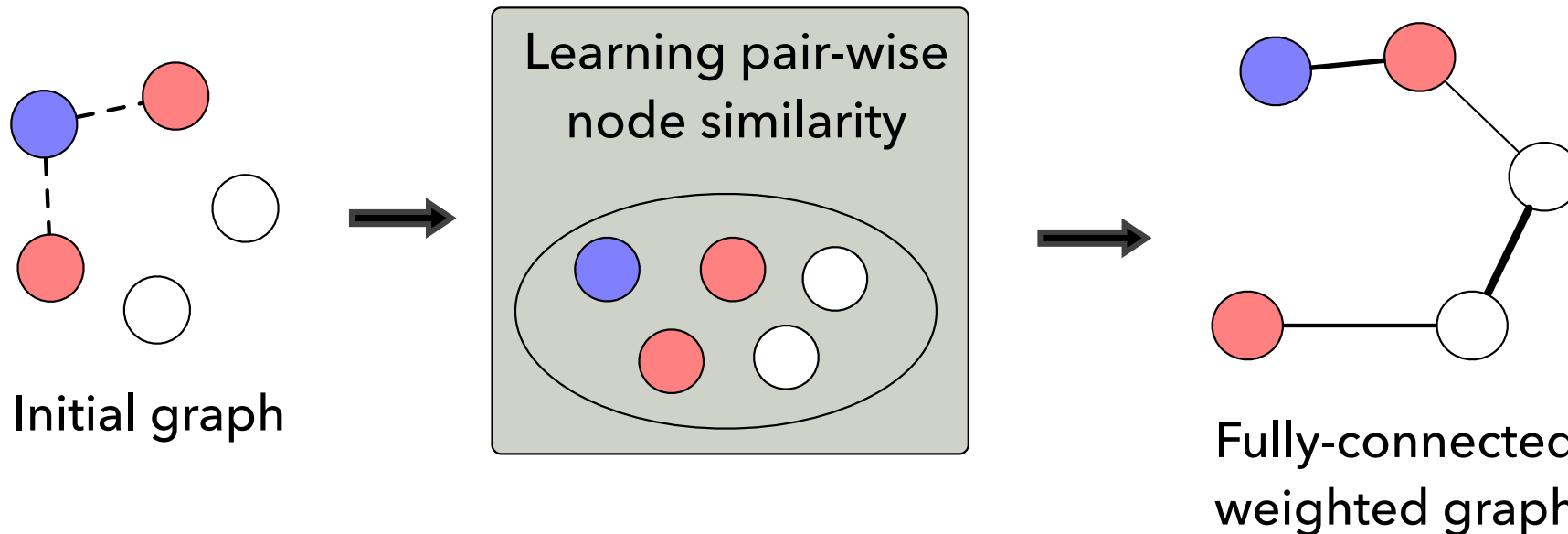
$$d(\mathbf{v}_i, \mathbf{v}_j) = \sqrt{(\mathbf{v}_i - \mathbf{v}_j)^\top M (\mathbf{v}_i - \mathbf{v}_j)}$$
$$S(\mathbf{v}_i, \mathbf{v}_j) = \frac{-d(\mathbf{v}_i, \mathbf{v}_j)}{2\sigma^2}$$

Gaussian kernel



# Structure-aware Similarity Metric Learning

- Learning a weighted adjacency matrix by computing the **pair-wise node similarity** in the embedding space
- Considering **existing edge information** of the intrinsic graph in addition to the node information

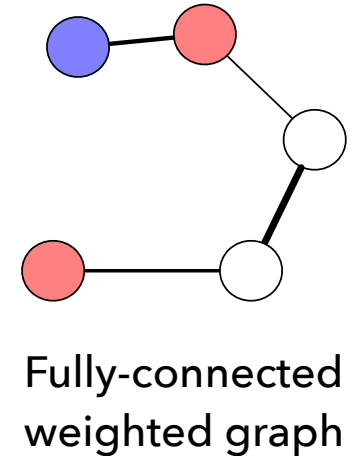
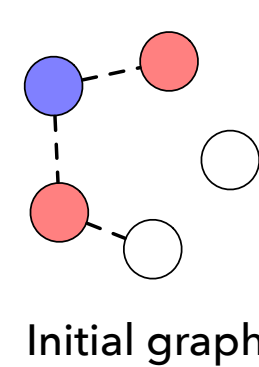


# Structure-aware Attention Mechanism

Variant 1)

$$S_{i,j}^l = \text{softmax}(\mathbf{u}^T \tanh(\mathbf{W}[\mathbf{h}_i^l, \mathbf{h}_j^l, \mathbf{v}_i, \mathbf{v}_j, \mathbf{e}_{i,j}]))$$

Edge embeddings

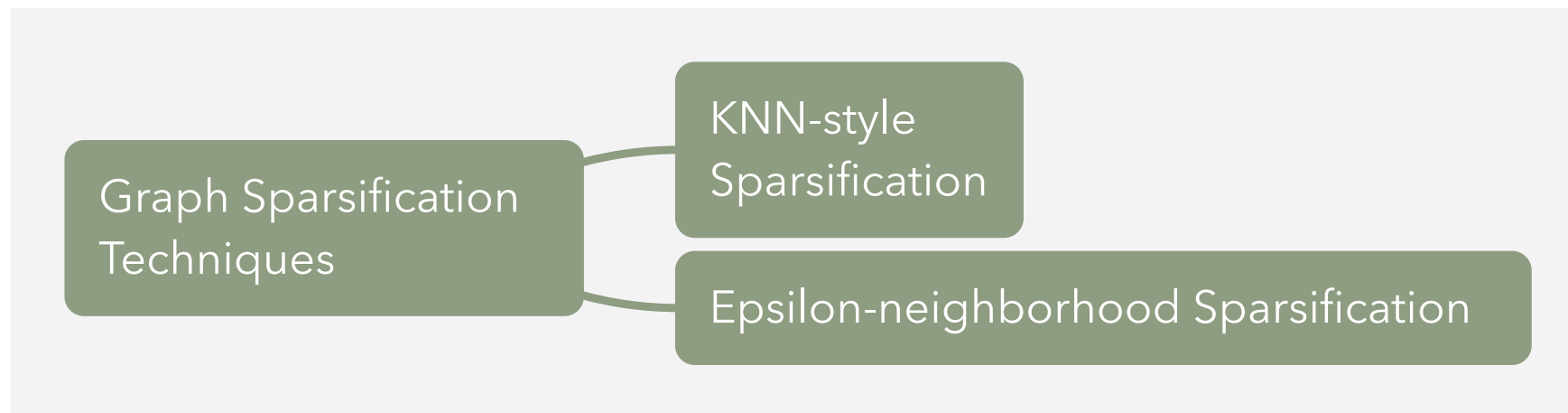


Variant 2)

$$S_{i,j} = \frac{\text{ReLU}(\mathbf{W}^Q \mathbf{v}_i)^T (\text{ReLU}(\mathbf{W}^K \mathbf{v}_i) + \text{ReLU}(\mathbf{W}^R \mathbf{e}_{i,j}))}{\sqrt{d}}$$

# Graph Sparsification Techniques

- Similarity metric functions learn a fully-connected graph
- Fully-connected graph is **computationally expensive** and might introduce **noise**
- Enforcing sparsity to the learned graph structure
- Various techniques



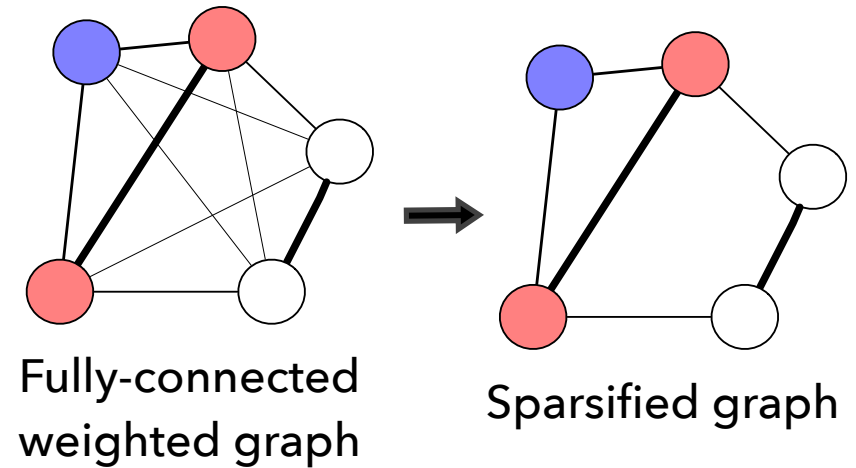
# Common Graph Sparsification Options

Option 1) KNN-style Sparsification

$$\mathbf{A}_{i,:} = \text{topk}(\mathbf{S}_{i,:})$$

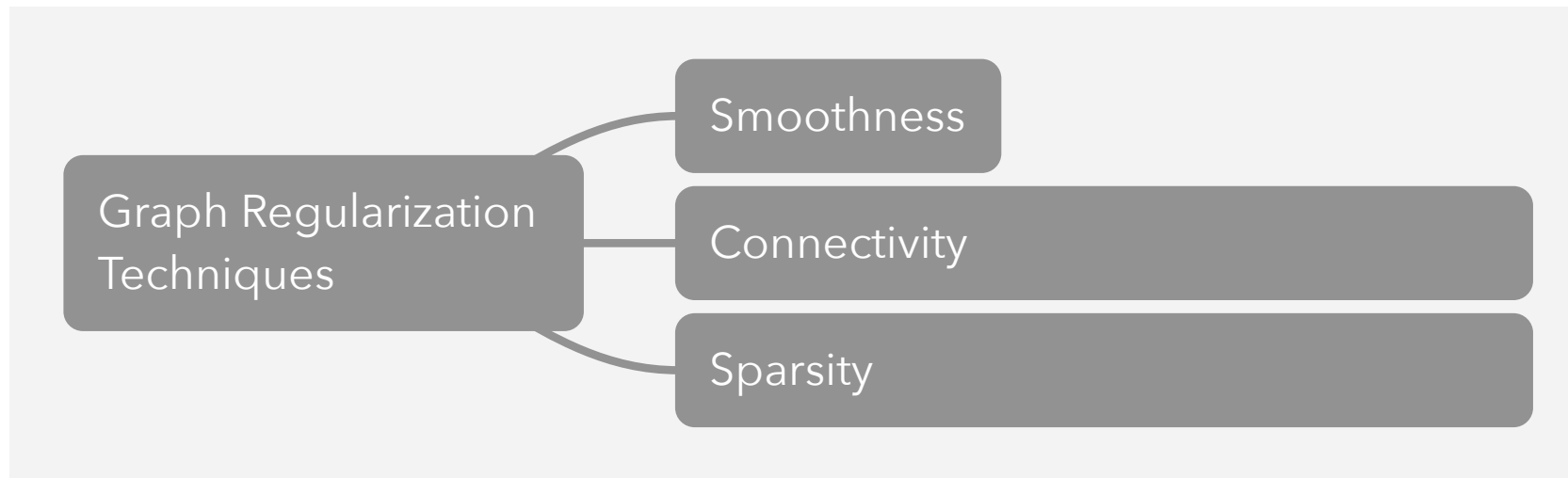
Option 2) epsilon-neighborhood Sparsification

$$A_{i,j} = \begin{cases} S_{i,j} & S_{i,j} > \varepsilon \\ 0 & \text{otherwise} \end{cases}$$



# Graph Regularization Techniques

- Enforcing **common graph properties** to the learned graph structure
- Combining both task prediction loss and graph regularization loss
- Various graph properties





# Graph Regularization Techniques

- Smoothness

$$\Omega(\mathbf{A}, \mathbf{X}) = \frac{1}{2n^2} \sum_{i,j} A_{i,j} \|\mathbf{X}_i - \mathbf{X}_j\|^2 = \frac{1}{n^2} \text{tr}(\mathbf{X}^\top \mathbf{L} \mathbf{X})$$

- Connectivity

$$-\frac{1}{n} \mathbf{1}^\top \log(\mathbf{A} \mathbf{1})$$

- Sparsity

$$\frac{1}{n^2} \|\mathbf{A}\|_F^2$$

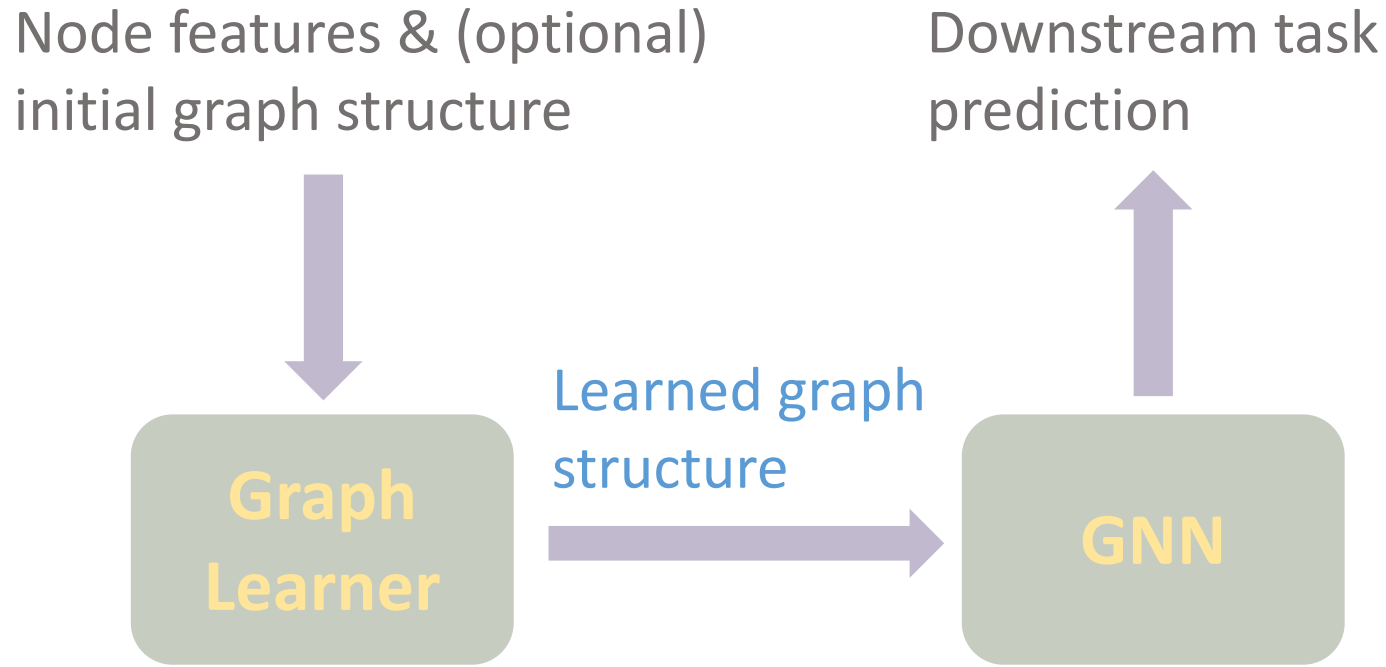
Borrowed from unsupervised GSL  
from smooth signals!

# Combining Intrinsic and Implicit Graph Structures

- Intrinsic graph typically still carries rich and useful information
- Learned implicit graph is potentially a “**shift**” (e.g., substructures) from the intrinsic graph structure

$$\tilde{A} = \lambda \underbrace{L^{(0)}}_{\text{Normalized graph Laplacian}} + (1 - \lambda) \underbrace{f(A)}_{f(A) \text{ can be arbitrary operation, e.g., graph Laplacian, row-normalization}}$$

# Learning Paradigms: Joint Learning



Chen et al. "GraphFlow: Exploiting Conversation Flow with Graph Neural Networks for Conversational Machine Comprehension". IJCAI 2020.

Chen et al. "Reinforcement Learning Based Graph-to-Sequence Model for Natural Question Generation". ICLR 2020.

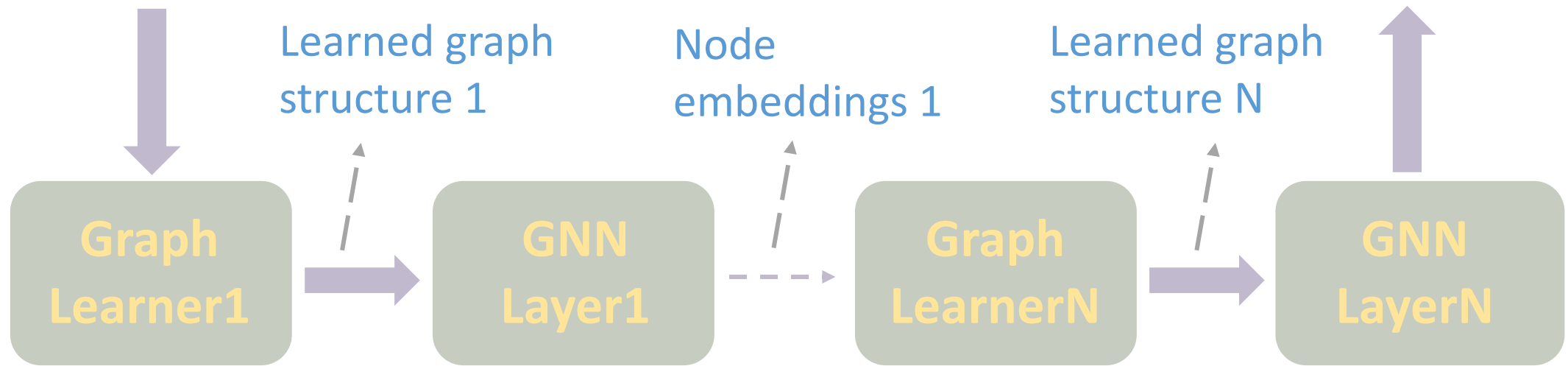
Liu et al. "Contextualized Non-local Neural Networks for Sequence Learning". AAAI 2019.

Liu et al. "Retrieval-Augmented Generation for Code Summarization via Hybrid GNN". ICLR 2021.

# Learning Paradigms: Adaptive Learning

Node features & (optional)  
initial graph structure

Downstream task  
prediction

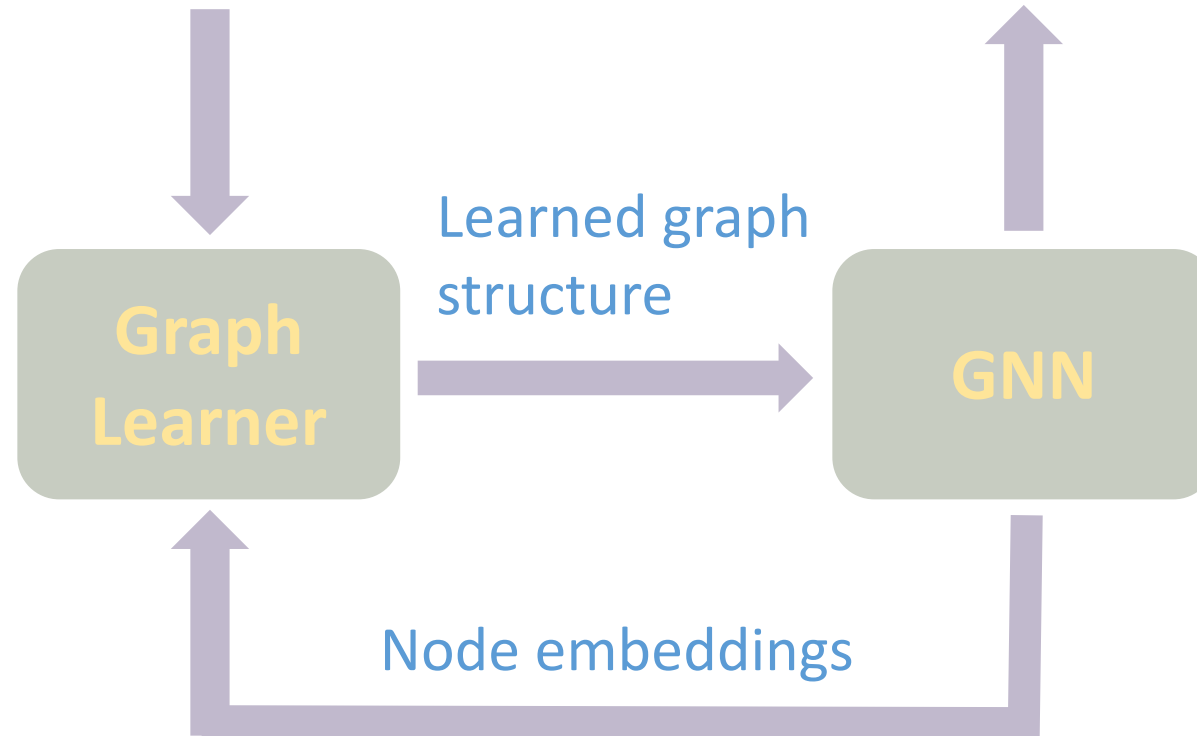


Repeat for fixed num. of stacked GNN layers

# Learning Paradigms: Iterative Learning

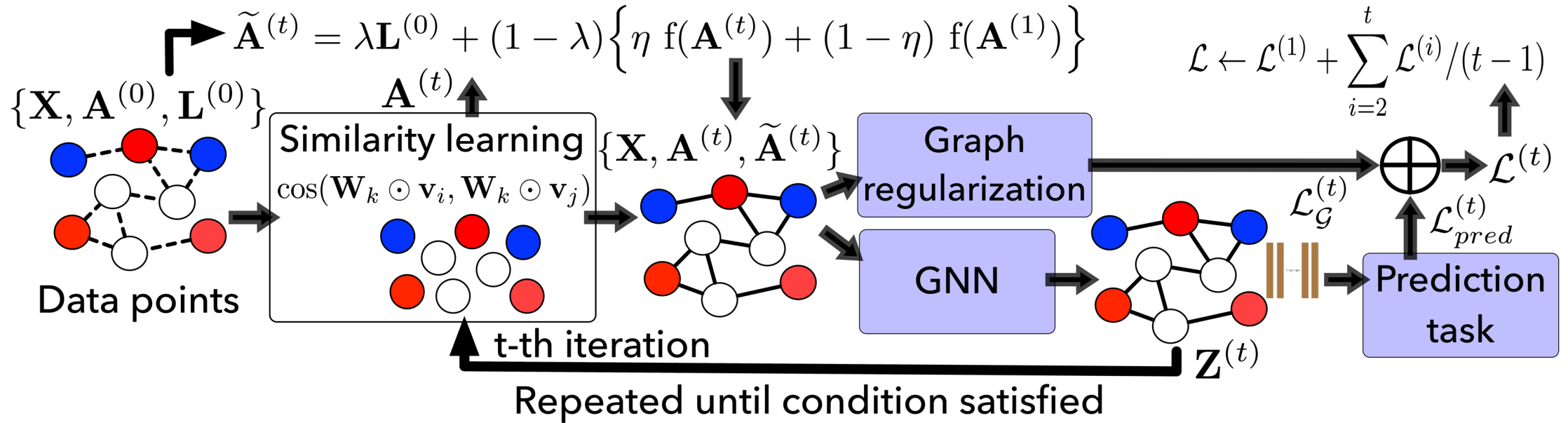
Node features & (optional)  
initial graph structure

Downstream task  
prediction



Repeat until condition satisfied

# Iterative Deep Graph Learning [Chen et al., NeurIPS 2020]

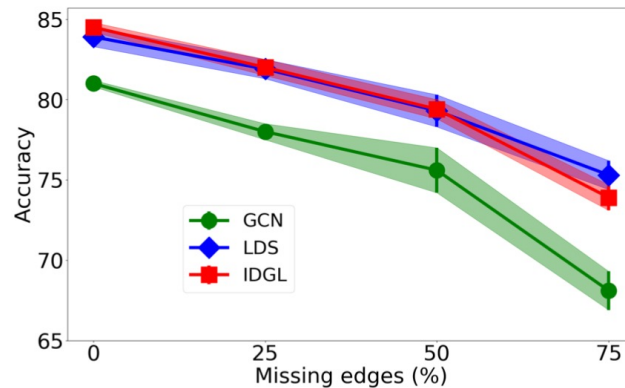


- GSL as **similarity metric learning**
- Graph regularization to **control smoothness, sparsity and connectivity**
- Iterative method to **refine the graph structure and graph embeddings**
- Better scalability ( $O(n^2) \rightarrow O(n)$ ) using **anchor-based approximation technique**

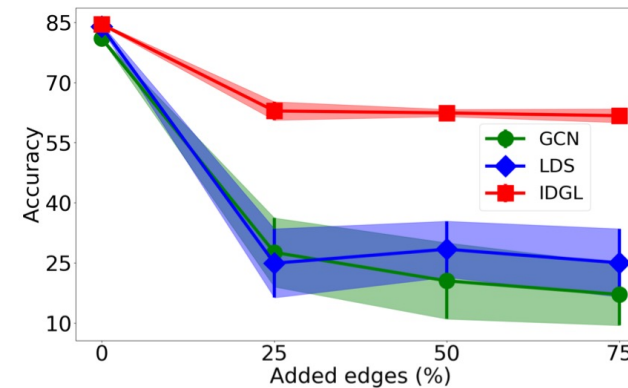
# Iterative Deep Graph Learning [Chen et al., NeurIPS 2020]

Model	Cora	Citeseer	Pubmed	ogbn-arxiv	Wine	Cancer	Digits
GCN	81.5	70.3	79.0	71.7 (0.3)	—	—	—
GAT	83.0 (0.7)	72.5 (0.7)	79.0 (0.3)	—	—	—	—
GraphSAGE	77.4 (1.0)	67.0 (1.0)	76.6 (0.8)	71.5 (0.3)	—	—	—
APNP	—	<b>75.7 (0.3)</b>	79.7 (0.3)	—	—	—	—
H-GCN	<b>84.5 (0.5)</b>	72.8 (0.5)	79.8 (0.4)	—	—	—	—
GCN+GDC	83.6 (0.2)	73.4 (0.3)	78.7 (0.4)	—	—	—	—
LDS	84.1 (0.4)	75.0 (0.4)	—	—	97.3 (0.4)	94.4 (1.9)	92.5 (0.7)
GCN <sub>kNN</sub> *	—	—	—	—	95.9 (0.9)	94.7 (1.2)	89.5 (1.3)
GAT <sub>kNN</sub> *	—	—	—	—	95.8 (3.1)	88.6 (2.7)	89.8 (0.6)
GraphSAGE <sub>kNN</sub> *	—	—	—	—	96.5 (1.1)	92.8 (1.0)	88.4 (1.8)
LDS*	83.9 (0.6)	74.8 (0.3)	—	—	96.9 (1.4)	93.4 (2.4)	90.8 (2.5)
IDGL	<b>84.5 (0.3)</b>	74.1 (0.2)	—	—	97.8 (0.6)	<b>95.1 (1.0)</b>	93.1 (0.5)
IDGL-ANCH	84.4 (0.2)	72.0 (1.0)	<b>83.0 (0.2)</b>	<b>72.0 (0.3)</b>	<b>98.1 (1.1)</b>	94.8 (1.4)	<b>93.2 (0.9)</b>

Node classification results.



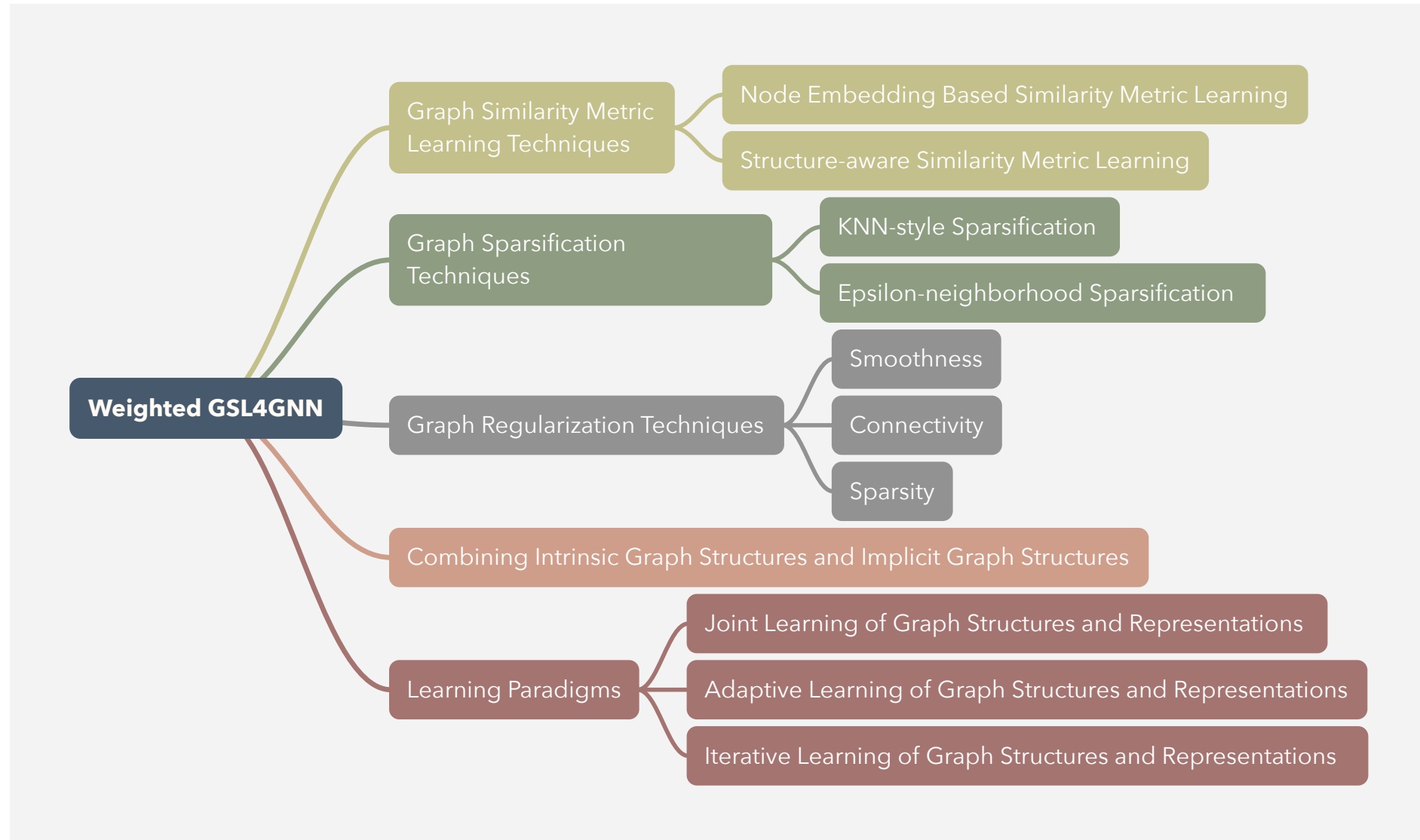
(a) Edge deletion



(b) Edge addition

Edge attack results on Cora.

# Weighted GSL4GNN Summary





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## **Connections to Other Problems**

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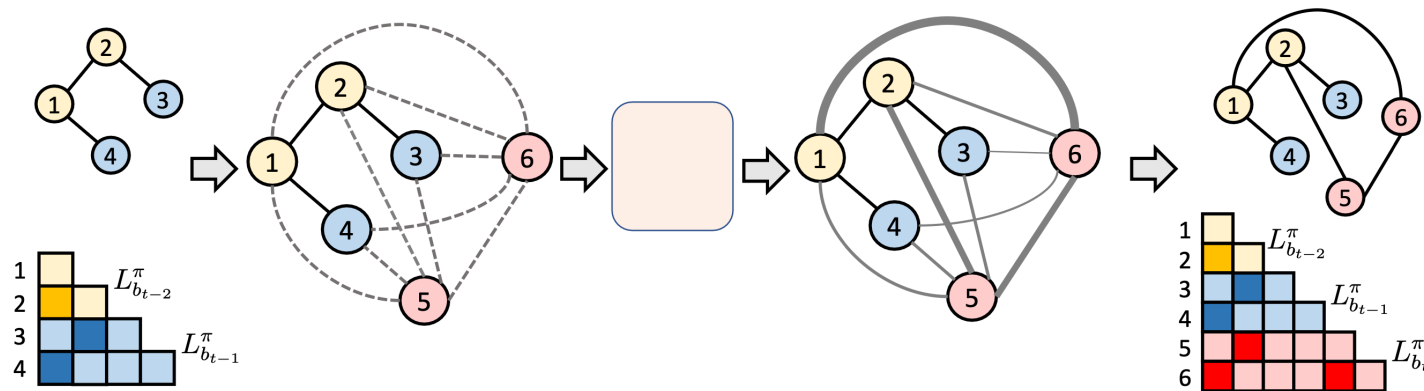
# Connections to Other Problems: GSL as Graph Generation

## Connections:

- Learning graphs from data

## Differences:

- Graph generation: **generating new graphs** where both nodes and edges are added by sampling from the learned graph distribution.
- GSL: **learning a graph structure** given a set of node attributes.



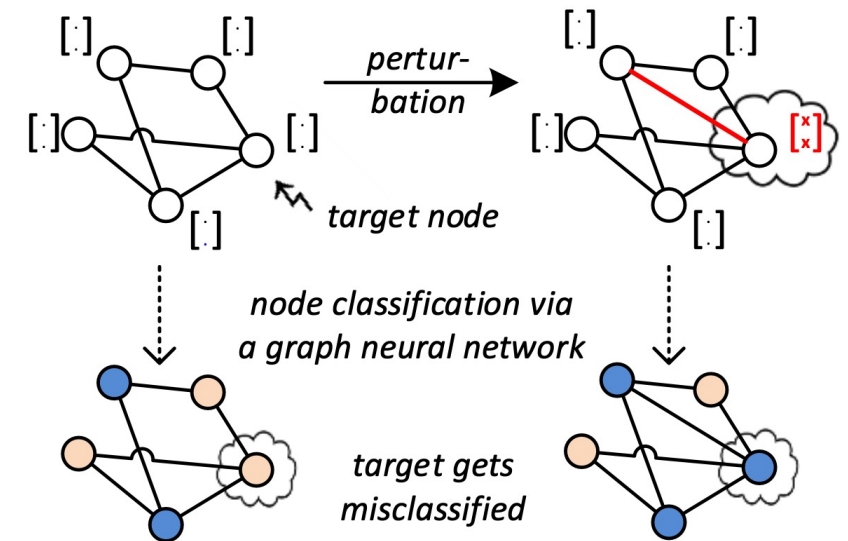
# Connections to Other Problems: GSL for Graph Adversarial Defenses

## Connections:

- Improving potentially error-prone (e.g., noisy or incomplete) input graphs
- Graph adversarial defenses can benefit from GSL techniques

## Differences:

- Graph adversarial defenses: initial graph structure is available, but potentially poisoned by adversarial attacks
- GSL: initial graph structure is available or unavailable



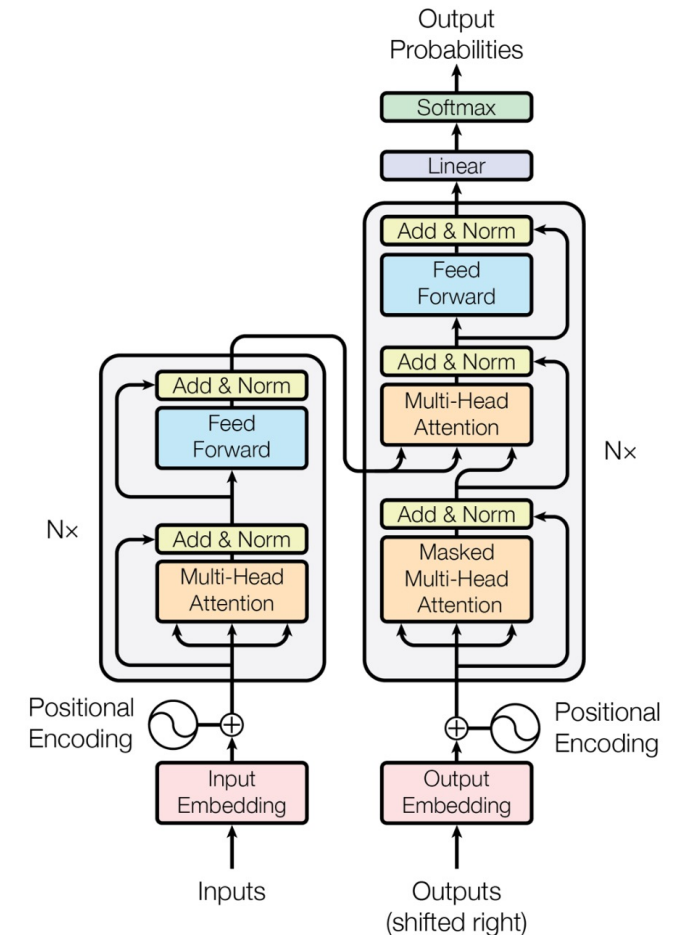
# Connections to Other Problems: Transformers

## Connections:

- Transformer models aim to learn a **self-attention matrix** between every pair of objects adaptively at each layer, similar to **adaptive learning paradigm** for weighted GSL

## Differences:

- Vanilla Transformers **don't handle graph-structured data** (graph transformers combining transformers and GNNs)



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# **GSL4GNN: Future Directions and Conclusions**

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# Future Directions

- Robust GSL
  - Noisy initial graph structures and noisy node attributes
- Scalable GSL
  - Pair-wise node similarity computation is expensive and intractable for large graphs
  - Potential solutions: LSH/low-rank/random feature/kernel methods
- GSL for Heterogeneous Graphs
  - Heterogeneous graphs carry on richer information
  - Less explored

# Conclusions

- GNNs are powerful machine learning tools for modeling graph-structured data
- GSL has been extensively studied in traditional machine learning
- GSL4GNN is a trending research area and critical for the success of GNN applications
- Open challenges in GSL4GNN

# Resources

- Chen, Yu, and Lingfei Wu. "Graph Neural Networks: Graph Structure Learning." *Graph Neural Networks: Foundations, Frontiers, and Applications*. Springer, Singapore, 2022. 297-321. ([website](#), [video](#))
- Zhu, Yanqiao, et al. "Deep graph structure learning for robust representations: A survey." *arXiv preprint arXiv:2103.03036* (2021).
- Dong, Guimin, et al. "Graph Neural Networks in IoT: A Survey." arXiv 2022.
- Wu, Lingfei, et al. "Deep Learning on Graphs for Natural Language Processing." Tutorials at NAACL'21, SIGIR'21, KDD'21, IJCAI'21, AAI'22 and TheWebConf'22. ([website](#))



Thanks!  
Q&A